

A. Kaimakamidis, Prof. I. Pitas
Aristotle University of Thessaloniki
pitas@csd.auth.gr
www.aiia.csd.auth.gr





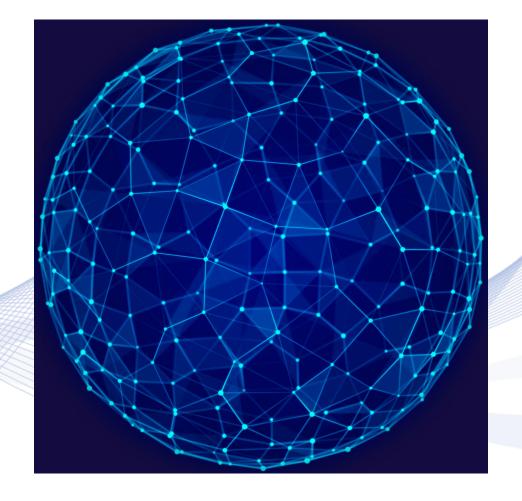
- Decentralized DNN Architectures
  - Federated Learning
  - Edge Computing
  - Peer-to-Peer Networks
- Knowledge Distillation
- Learning-by-Education Node Community (LENC) Framework
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  - Edge Computing Decentralized Inference
  - Reproducibility Privacy
  - Deep Learning Tasks Supported by LENC Framework
- Experimental Evaluation





#### Definition:

Decentralized Deep Neural Network (DNN) architectures distribute computation and decision-making across multiple nodes or devices, offering advantages in scalability, privacy, and robustness.

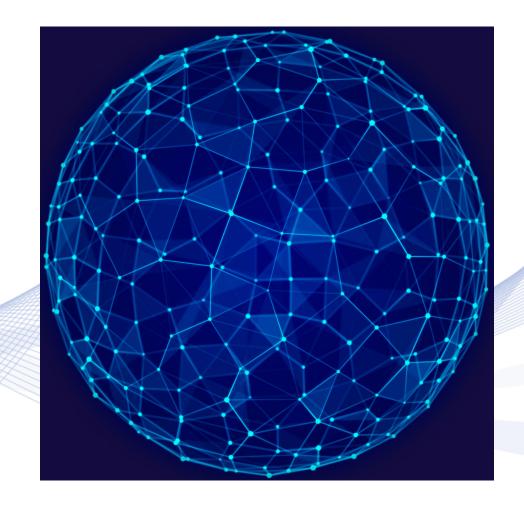






#### Characteristics:

- Distribution: Computation and data are spread across multiple nodes or devices.
- Collaboration: Nodes cooperate to train or execute models.
- Privacy Preservation: Data remains localized, enhancing privacy and security.
- Fault Tolerance: Resilience to individual node failures or attacks.

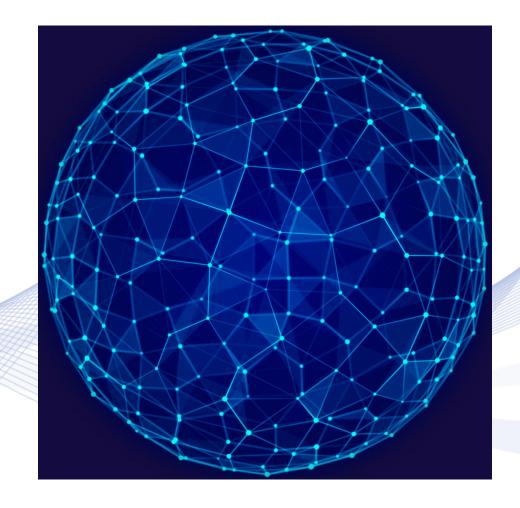






#### Types:

- 1. Federated Learning: Training a global model across decentralized devices while keeping data on-device.
- 2. Edge Computing: Running inference or lightweight training directly on edge devices.
- 3. Peer-to-Peer Networks: Collaborative learning among peers without a central server.





### **Federated Learning**



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### **Federated Learning**



- Privacy Preservation: Data remains on local devices, ensuring privacy.
- Efficiency: Reduces the need to transfer large volumes of data to a central server.
- Scalability: Suitable for large-scale distributed systems with diverse data sources.
- Adaptability: Can accommodate non-IID (non-identically distributed) data across devices.





## **Edge Computing**



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- Low Latency: Enables real-time decisionmaking without reliance on distant servers.
- Bandwidth Efficiency: Reduces the need to transfer large volumes of data to central servers.
- Privacy Preservation: Sensitive data can be processed locally, enhancing privacy.
- Offline Capability: Allows for operation in disconnected or low-connectivity environments.





#### Peer-to-Peer Networks



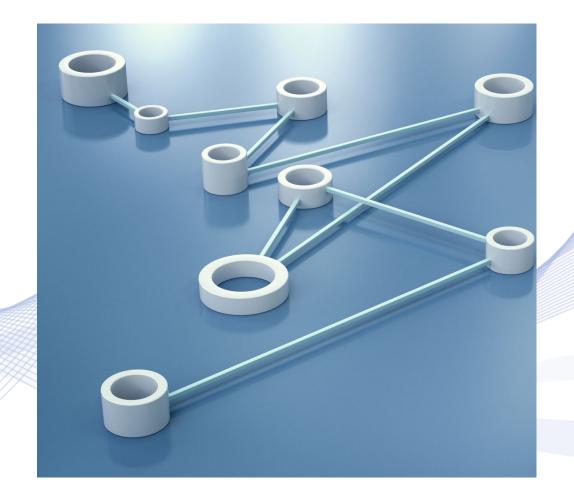
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- Decentralization: Reduces dependency on central servers, enhancing scalability and robustness.
- Resource Efficiency: Utilizes idle computational resources across peers.
- Resilience: Resilient to node failures or attacks due to distributed nature.
- Community-driven Innovation: Facilitates collaborative research and knowledge exchange.





### **Knowledge Distillation**



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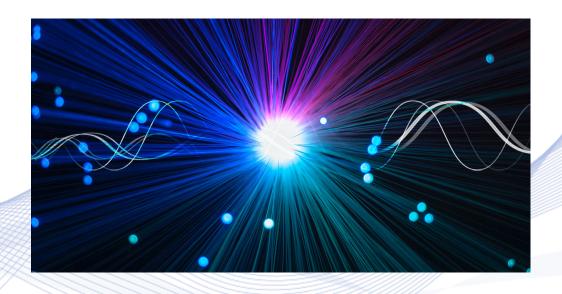






#### Definition:

Knowledge Distillation is a technique in machine learning where a compact model, known as the student model, learns from a larger, more complex model, referred to as the teacher model, by mimicking its outputs or internal representations.



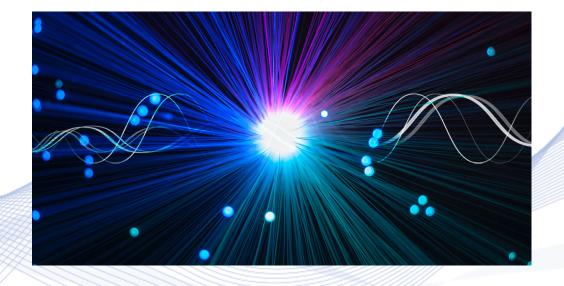






#### Process:

- 1. Teacher-Student Setup.
- 2. Training: The student model is trained using a combination of the original training data and the teacher model's predictions or intermediate representations.
- 3. Objective Function: The objective is to minimize the discrepancy between the student's predictions and the teacher's outputs or representations.



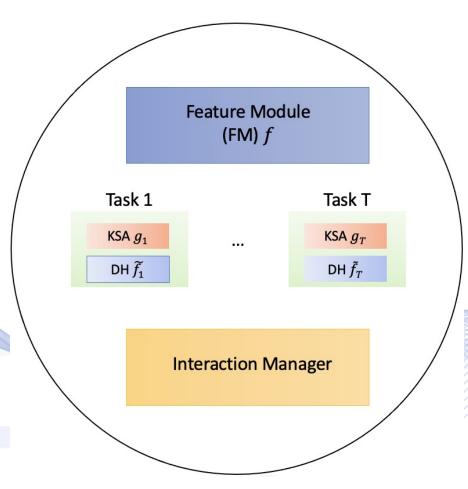




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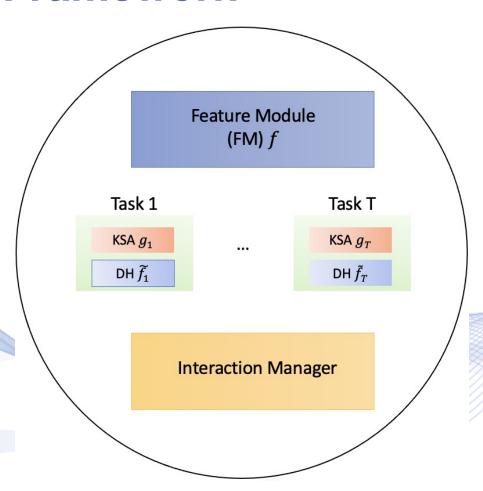




- External environment data streams  $\mathcal{D}_s$ .
- DNN nodes
  - Feature Module (FM) f.
  - Decision Heads (DH)  $\tilde{f}_i$ ,  $i = 1, \dots, T$ .
  - Knowledge Self-Assessment (KSA) Modules  $g_i$ ,  $i = 1, \dots, T$ .
  - Interaction Manager.



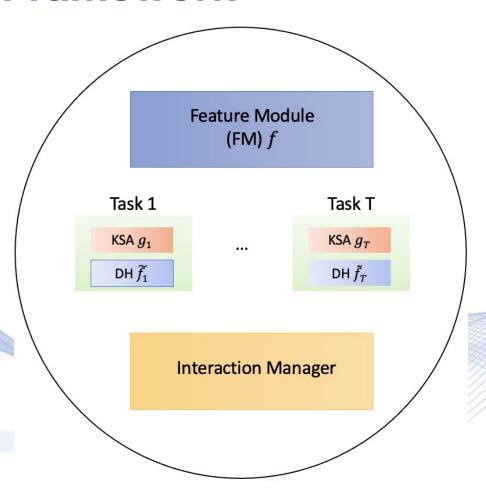




- Knowledge Self-Assessment Modules
  - The KSA Modules consist of an Out-of-Distribution (OOD) detector  $g_i(x)$ :  $\mathcal{X}_i \rightarrow \{0,1\}, i = 1, \dots, T$ .
  - This module classifies new data samples  $x \in \mathcal{X}_i$ ,  $i = 1, \dots, T$  as in or out of distribution.



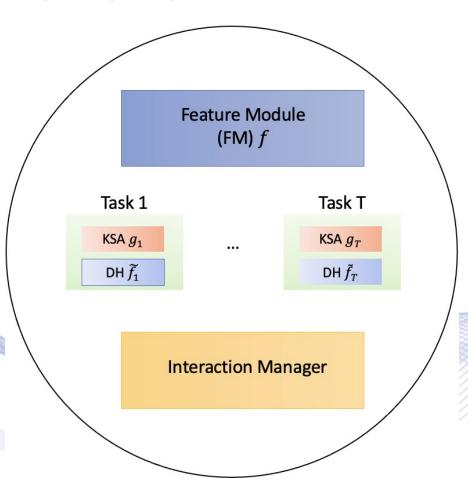




- Knowledge Self-Assessment Modules
  - The KSA module is used to automatically detect which DH  $\tilde{f}_i$ ,  $i=1,\cdots,T$  will be used for decision making.
  - We define  $j = argmax(g_1, \dots, g_T)$ , where j is the index of the task trained on sample data that were like the ones found in  $\mathcal{X}_i$ .





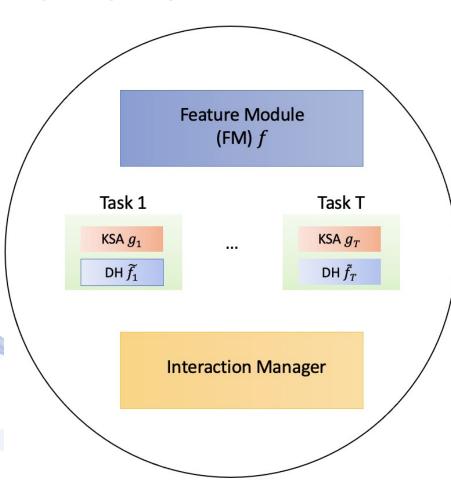


#### Feature Module

- Shared DNN f among tasks, parametrized by  $w_s$ .
- Decision Heads  $\tilde{f}_i$ ,  $i = 1, \dots, T$ , parametrized by  $w_i$ .
- Decision (Inference):  $\tilde{y}_j = \tilde{f}_j(f(x; w_s); w_j)$ , for an input vector x, where  $j = argmax(g_1, \dots, g_T)$ .



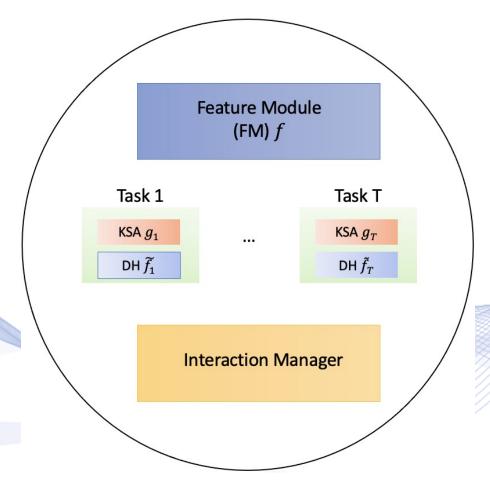




#### Interaction Manager

- Handles the communications among the nodes.
- Handles the communications among the nodes and the external environment.







- Interaction Manager
- Three Key Functions:
  - Receives data streams  $\mathcal{D}^s$  from the environment.
  - Transmits the data streams  $\mathcal{D}^s$  to other nodes and receives their responses  $\{q_j, j = 1, \dots, N, i \neq j\}$ , where N is the number of nodes and i is the current node.
  - Sends and receives node components, such as data, activations, weights and structure.



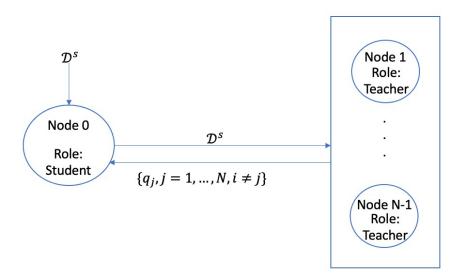


#### Interaction Manager

- Possible ways to compute  $q_n$  for each LENC node:
- a) Average Accuracy
   Stored average classification accuracy over past tasks.
- b) OOD Score Function of out-of-distribution score from the KSA module, using  $\mathcal{D}^s$
- c) Prediction Disagreement (Churn)
   Accuracy of student predictions on D<sup>s</sup> using the teacher node outputs as pseudo-ground-truth.



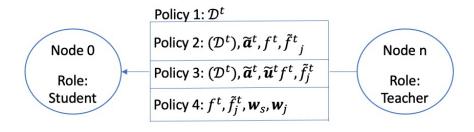




- External Environment sends data stream  $\mathcal{D}_s$ .
- Node's KSA Module checks if the distribution is known.
- If not the data stream is sent to other nodes.
- The nodes respond with  $\{q_j, j = 1, \dots, N, i \neq j\}$ .
- The student node selects a teacher node.



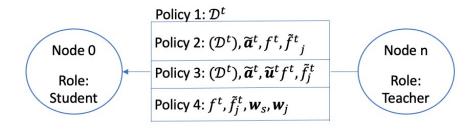




- Option 1: Data Transmission
  - The teacher node sends its training data  $\mathcal{D}^t$ .
  - The student node uses the training data to learn the task.



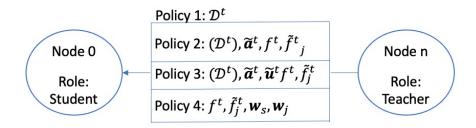




- Option 2: Soft-Output Activation Transmission
  - The teacher node sends its training data  $\mathcal{D}^t$ , its soft-output activations  $\tilde{a}^t$  and its structure  $f^t$  and  $\tilde{f}_i^t$  for the task j.
  - The student node uses KD to for training using the teacher's guidance.



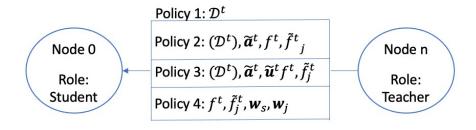




- Option 3: Feature Activation Transmission
  - The teacher node sends its training data  $\mathcal{D}^t$ , its soft-output activations  $\tilde{\boldsymbol{a}}^t$ , its feature activations  $\tilde{\boldsymbol{u}}^t$  and its structure  $f^t$  and  $\tilde{f}_i^t$  for the task j.
  - The student node uses KD to for training using the teacher's guidance.







- Option 4: Weights Transmission
  - The teacher node its structure  $f^t$  and  $\tilde{f}_j^t$  and its weights  $\xi_s$  and  $\xi_j$  for the task j.
  - The student node is now a copy of the teacher node's model.





LENC selects the appropriate knowledge transfer policy based on user-defined environmental conditions.

Key Questions:

- 1. Are there privacy limitations on the model, dataset, or parameters?
- 2. Are there network traffic limitations?
- 3. Is there a latency requirement for instant transfer?





#### Policy Selection Logic:

- Policy 2 (Default)
  - Use when strong privacy restrictions apply
  - Only the first input option  $(D^s \rightarrow \text{soft activations})$
  - Works with any architecture or dataset

- Policy 3
  - Use if the teacher and student share architecture
  - More effective guidance
  - Second input  $(D_j^t)$  allowed only if no privacy or traffic limitations





#### Policy Selection Logic:

- Policy 4
   Use if all apply:
  - Latency-sensitive
  - No privacy limits
  - Student is untrained

Training-free option

- Policy 1
   Use if all apply:
  - No privacy or traffic limits
  - Teacher's architecture can be shared
  - Student > Teacher in model complexity



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- Define a node as a master node.
- All nodes with the same structure within the community train themselves using their local data.
- The master node uses Option 4 to receive the weights of all nodes with the same structure within the community.
- The master node aggregates the weights of all participating nodes.
- The process is repeated until convergence.



#### Peer-to-Peer Networks



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- Options 1-4 constitute forms of Peer-to-Peer Network interactions.
- Nodes act exclusively to enhance their knowledge.
- No need for a central server.
- Retaining knowledge within the node community.



## **Continual Learning**



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## **Continual Learning**



Task 1



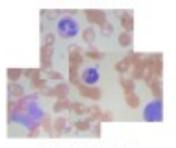
Scenes 67 classes; 15.620 images

Task 2



Birds 200 classes; 11,788 images

Task k-1



Blood Cell 4 classes; 12,500 images

Task k



Cars 196 classes; 16,185 images

Task k+1



SVHN 10 classes; 99,289 images



# Edge Computing – Decentralized Inference



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# Edge Computing – Decentralized Inference



- Raw data is processed locally on nodes.
- Nodes use real-time inference on their data.
- Lightweight training of Feature Modules directly on nodes.
- A master node (server) can be defined to aggregate inference results.
- Generating responses or actions locally without centralized decision-making.







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### Reproducibility - Privacy

- DNN node 1 is the model of a published paper.
- DNN node 2 wants to replicate the model and the experiments.
- Using variations of Options 1-4 DNN node 2 can replicate the initial model and also consider possible privacy constraints.
- Private weights, architecture, training dataset, etc.



## Deep Learning Tasks using the LENC Framework

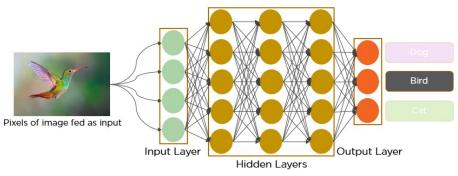


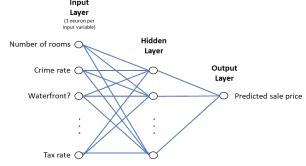
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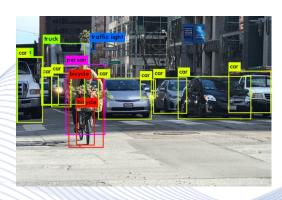
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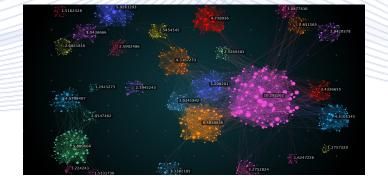














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Datasets: CIFAR-10 & CIFAR-100.

Architectures: ResNet-18 (teacher), WRN-16-4, VGG11, and additional ResNet-18s (students).

#### **Key Details:**

- Pretrained ResNet-18 used as the sole teacher
- Competing CKD methods adapted to use teacher responses (not ground-truth).
- Two stream sizes: 1,000 & 5,000 data points from the teacher's training set.
- 10 sequential data streams  $\mathcal{D}_s$ , each triggering a knowledge cycle



## Experimental Evaluation (VML)

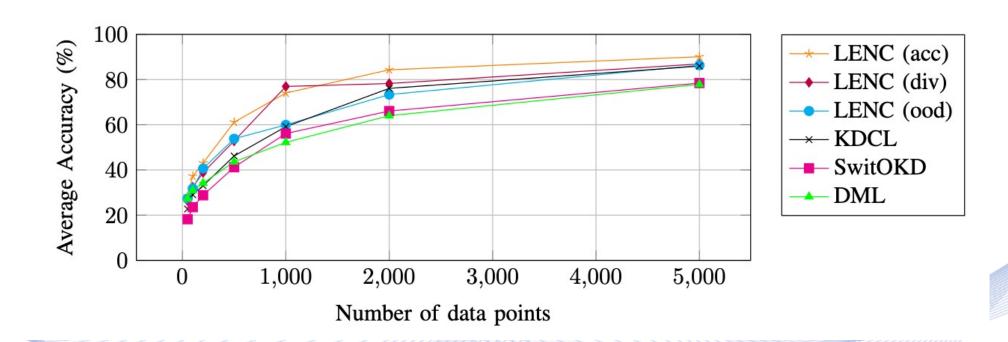


Dataset	Students	Stream Size	DML	KDCL	SwitOKD	LENC (proposed)
CIFAR-10	ResNet-18 & ResNet-18 WRN-16-4 & VGG11	1000	52.20±0.52 51.17±0.71	$62.23 \pm 0.15 \\ 62.09 \pm 0.21$	56.15±0.73 57.85±0.80	$76.93 {\pm} 0.71 \\ 70.16 {\pm} 0.82$
	ResNet-18 & ResNet-18 WRN-16-4 & VGG11	5000	$77.85\pm0.31$ $75.56\pm0.82$	$85.76\pm0.07$ $84.47\pm0.08$	$79.08\pm0.70$ $78.79\pm0.68$	$\begin{array}{c} 86.31 \pm\ 0.32 \\ 87.12 {\pm} 0.24 \end{array}$
CIFAR-100	ResNet-18 & ResNet-18 WRN-16-4 & VGG11	1000	$9.77 \pm 0.25$ $6.12 \pm 0.38$	$25.16\pm0.12$ $27.59\pm0.19$	13.71±0.57 14.72±0.61	$34.96\pm0.47 \ 29.75\pm0.49$
	ResNet-18 & ResNet-18 WRN-16-4 & VGG11	5000	31.53±0.31 8.30±0.16	$58.70\pm0.09$ $56.94\pm0.12$	35.31±0.29 37.27±0.45	$65.02{\pm}0.13 \ 58.18{\pm}0.17$

Comparisons of LENC with competing CKD methods, for incoming data streams Ds of sizes 1000 and 5000. The average test accuracy (%) of the student nodes is reported.







Average student LENC node classification accuracy (%) for varying Ds sizes in the CIFAR-10 dataset. The 3 alternative LENC teacher selection policies are compared against competing methods.





- Comparisons of the LENC knowledge transfer policies, for incoming data streams  $\mathcal{D}_s$  of sizes 100, 500, 1000, 5000, and 60000 (full dataset).
- Policies 2-3 are independently evaluated with both unlabeled (using  $\mathcal{D}_s$ ) and labeled (using  $\mathcal{D}_j^t$ ) input options.
- The average test classification accuracy (%) of the student LENC nodes is reported.

Dataset	Stream Size	Policy 1	Policy 2	Policy 3
$\overline{\mathcal{D}_{j}^{t}}$	60000	91.97	93.72	93.59
,	60000	_	91.86	92.07
	100	-	37.75	37.11
$\mathcal{D}^s$	500	-	61.13	62.48
	1000	-	74.04	74.29
	5000	i <b>-</b>	90.15	90.05

Student LENC node classification accuracy (%) for varying Ds sizes in the CIFAR-10 dataset. The 3 alternative knowledge transfer policies are examined.



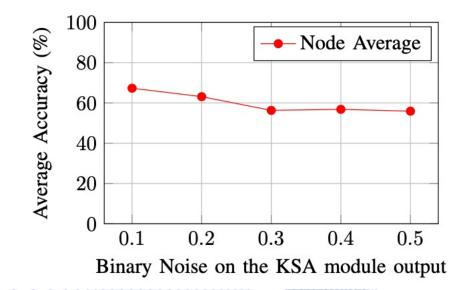


#### Experiment Setup:

- Repeated the CKD experiment.
   Used two untrained ResNet-18 students.
- Data stream: 1,000 CIFAR-10 samples.
- Simulated KSA failure by injecting binary noise into KSA outputs.

#### **Key Observation:**

- LENC remained robust despite KSA corruption.
- Only a slight drop in average accuracy was observed.



KSA module robustness analysis by adding binary noise to the KSA modules' output.



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#### Q & A

Thank you very much for your attention!

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Contact: Prof. I. Pitas pitas@csd.auth.gr

