

Hybrid & Causal ML in the Earth sciences

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Outline

- Part I - ML for Earth sciences
- Part II - Physics-aware Machine Learning
 1. Encode domain knowledge
 2. Emulate complex codes
 3. Learn parametrizations
- Part III – Causal Machine Learning
 1. Learning causal representations
 2. Causal discovery in the wild
 3. Causality with LLMs
- Part IV - Conclusions

Part I

ML for the Earth sciences

Opportunities & challenges

Earth science



Earth observation





DL in Earth and climate sciences – the promise!

PERSPECTIVE

<https://doi.org/10.1038/s41586-019-0912-1>

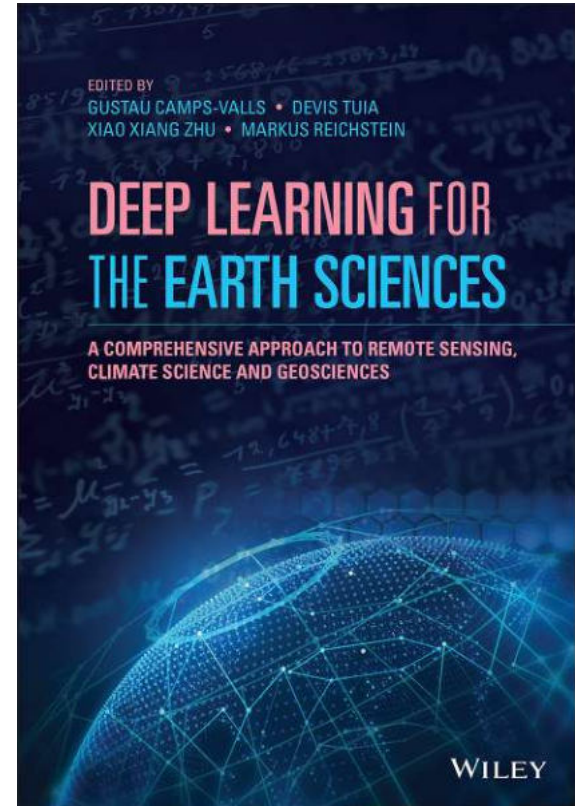
Deep learning and process understanding for data-driven Earth system science

Markus Reichstein^{1,2*}, Gustau Camps-Valls³, Bjørn Stevens⁴, Martin Jung¹, Joachim Denzler^{2,5}, Nuno Carvalhais^{1,6} & Prabhat⁷

Machine learning approaches are increasingly used to extract patterns and insights from the ever-increasing stream of geospatial data, but current approaches may not be optimal when system behaviour is dominated by spatial or temporal context. Here, rather than amending classical machine learning, we argue that these contextual cues should be used as part of deep learning (an approach that is able to extract spatio-temporal features automatically) to gain further process understanding of Earth system science problems, improving the predictive ability of seasonal forecasting and modelling of long-range spatial connections across multiple timescales, for example. The next step will be a hybrid modelling approach, coupling physical process models with the versatility of data-driven machine learning.

Reichstein, Camps-Valls et al, Nature, 2019

Camps-Valls, Tuia, Xiang, Reichstein. Wiley & Sons book, 2021



DL in Earth sciences – solved!

Chaos

ARTICLE

scitation.org/journal/cha

LETTER

<https://doi.org/10.1038/s41586-019-1559-7>

Forecasting of extreme flood events using different satellite precipitation products and wavelet-based machine learning methods

Cite as: *Chaos* 30, 063115 (2020); doi: [10.1063/5.0008195](https://doi.org/10.1063/5.0008195)
Submitted: 19 March 2020 · Accepted: 14 May 2020
Published Online: 2 June 2020

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Article | [Open Access](#) | [Published: 29 September 2021](#)

Skilful precipitation nowcasting using deep generative models of radar

[Suman Ravuri](#), [Karel Lenc](#), [Matthew Willson](#), [Dmitry Kangin](#), [Remi Lam](#), [Piotr Mirowski](#), [Megan Fitzsimons](#), [Maria Athanassiadou](#), [Sheleem Kashem](#), [Sam Madge](#), [Rachel Prudden](#), [Amol Mandhane](#), [Aidan Clark](#), [Andrew Brock](#), [Karen Simonyan](#), [Raja Hadsell](#), [Niall Robinson](#), [Ellen Clancy](#), [Alberto Arribas](#) & [Shakir Mohamed](#) 

[Nature](#) 597, 672–677 (2021) | [Cite this article](#)

Deep learning for multi-year ENSO forecasts

Yoo-Geun Ham^{1,4}, Jeong-Hwan Kim¹ & Jing-Jia Luo^{2,3}

PHYSICAL REVIEW RESEARCH 4, 023028 (2022)

Predicting extreme events from data using deep machine learning: When and where

Junjie Jiang ^{1,2} Zi-Gang Huang ¹ Celso Grebogi ³ and Ying-Cheng Lai ^{2,4,*}

Science

RESEARCH ARTICLE



Cite as: R. Lam *et al.*, *Science* 10.1126/science.adi2336 (2023).

Learning skillful medium-range global weather forecasting

Remi Lam^{1†}, Alvaro Sanchez-Gonzalez^{2†}, Matthew Willson^{3†}, Peter Wirsberger^{4†}, Meire Fortunato^{5†}, Ferran Alet^{6†}, Suman Ravuri^{7†}, Timo Ewalds⁸, Zach Eaton-Rosen⁹, Weihua Hu¹, Alexander Merose², Stephan Hoyer², George Holland¹, Oriol Vinyals¹, Jacklynn Stott¹, Alexander Pritzel¹, Shakir Mohamed^{1*}, Peter Battaglia^{1*}

Earth sciences – the *what*, but also the *why* & *how* questions

- Predict weather / essential climate variables
- Being consistent with domain knowledge
- Understand processes by emulation/parametrization
- Characterize and explain extreme events
- Learn meaningful/causal representations
- Discover causal relations from data
- Attribute causes of changes and anomalies



Earth sciences – not yet!

- **Predict weather / essential climate variables**
- **Being consistent with domain knowledge**
- **Understand processes by emulation/parametrization**
- **Characterize and explain extreme events**
- **Learn meaningful/causal representations**
- **Discover causal relations from data**
- **Attribute causes of changes and anomalies**

Part II

Part III

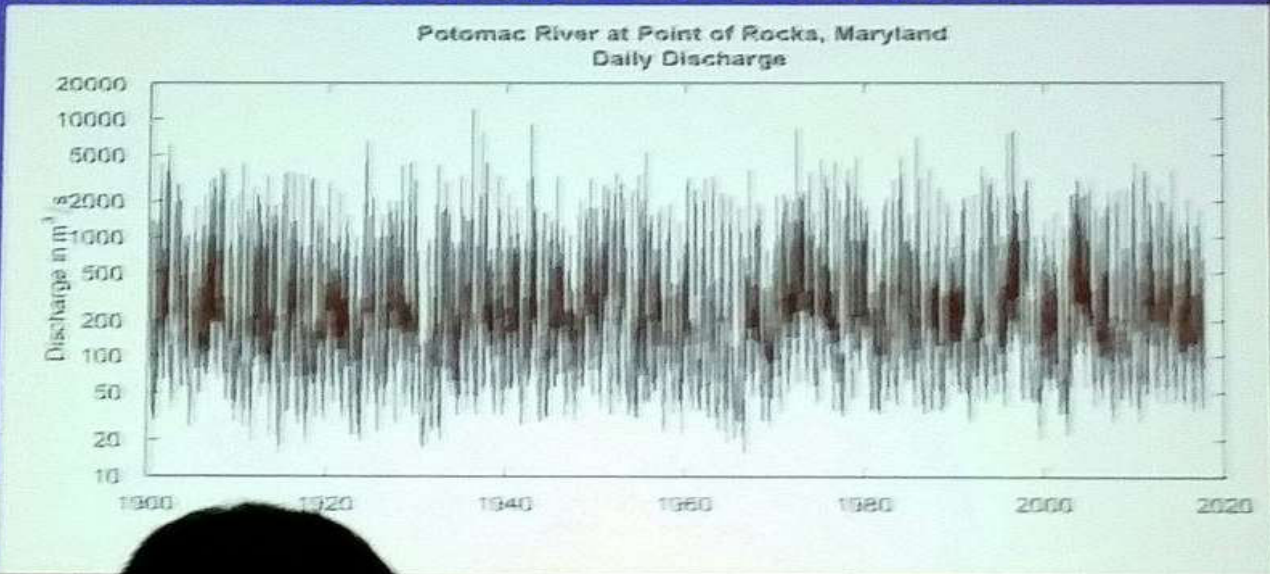
Part II

Physics-aware ML

* aka physics-guided/informed, domain/science-guided, ...

**“Models without data are fantasy.
Data without models are chaos.”**

Patrick Crill,
Stockholm
University, quoted in
Science, 2014, in
“Methane on the rise
again”, vol 343, pp.
493-495



Deep learning and process understanding for data-driven Earth system science

Markus Reichstein^{1,2*}, Gustau Camps-Valls³, Bjorn Stevens⁴, Martin Jung¹, Joachim Denzler^{2,5}, Nuno Carvalhais^{1,6} & Prabhat⁷

Machine learning approaches are increasingly used to extract patterns and insights from the ever-increasing stream of geospatial data, but current approaches may not be optimal when system behaviour is dominated by spatial or temporal context. Here, rather than amending classical machine learning, we argue that these contextual cues should be used as part of deep learning (an approach that is able to extract spatio-temporal features automatically) to gain further process understanding of Earth system science problems, improving the predictive ability of seasonal forecasting and modelling of long-range spatial connections across multiple timescales, for example. The next step will be a hybrid modelling approach, coupling physical process models with the versatility of data-driven machine learning.

1. Encoding domain knowledge

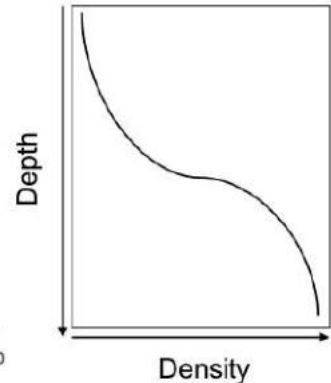
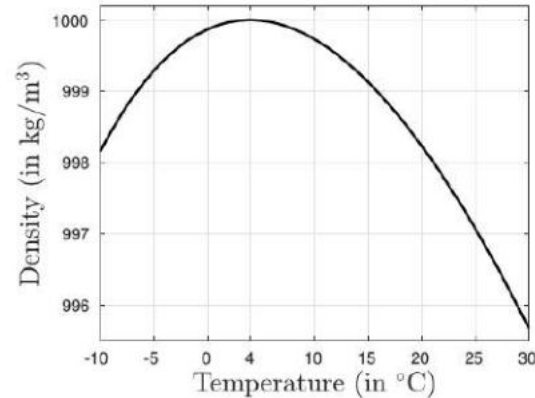
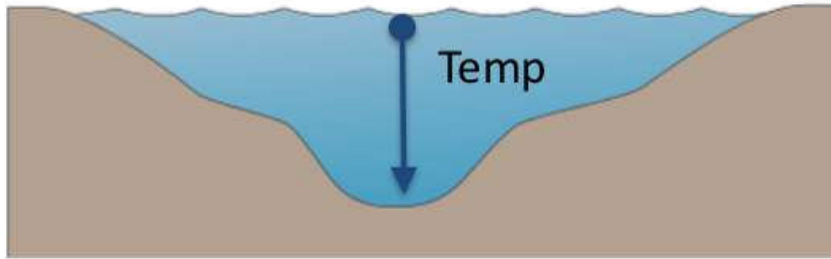
Constrained optimization & hybrid modeling

A- Constrained optimization

- ML minimizing model errors & violations of the physical laws

$$\text{PhysLoss} = \text{Cost}(y, \hat{y}) + \lambda_1 \|w\|_2^2 + \gamma \Omega(\hat{y}, \Phi)$$

$\Omega(\hat{y}, \Phi) = \text{sum of physical violations of } \hat{y}$



B- Fair optimization

- ML minimizing errors & predictions independent of sensitive factors

$$\text{FairLoss} = \text{Cost}(y, \hat{y}) + \lambda_1 \|w\|_2^2 + \gamma I(\hat{y}, s)$$

- Independence measured with HSIC

$$I := \text{HSIC}(\mathcal{Y}, \mathcal{H}, \mathbb{P}_{\mathbf{y}s}) = \|\mathbf{C}_{\mathbf{y}s}\|_{\text{HS}}^2$$

- Closed form solution with kernels

$$\Lambda = (\tilde{\mathbf{K}} + \lambda \mathbf{I} + \frac{\mu}{n^2} \tilde{\mathbf{K}} \tilde{\mathbf{K}}_s)^{-1} \mathbf{Y}$$

- Probabilistic interpretation with GPs:

$$f \sim \mathcal{GP}(0, k(\cdot, \cdot) - k_{\mathbf{x}}^{\top} (\mathbf{KHLH} + \delta^{-1} \mathbf{I})^{-1} \mathbf{HLH} k_{\mathbf{x}})$$

“Fair Kernel Learning” Perez, Laparra, Gomez, Camps-Valls, G. ECML, 2017.

“Consistent Regression of Biophysical Parameters with Kernel Methods” Díaz, Pérez-Suay, Laparra, Camps-Valls, IGARSS 2018

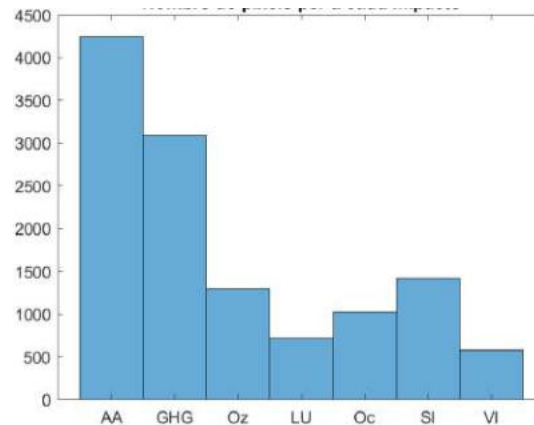
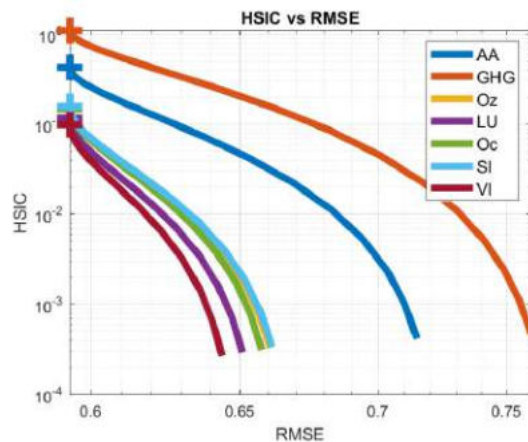
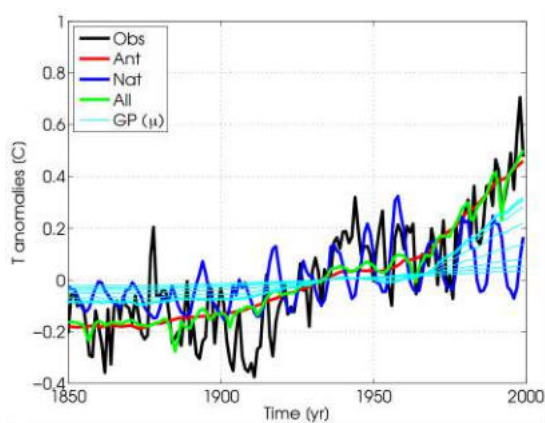
“Physics-aware Nonparametric Regression Models for Earth Data Analysis”. Cortés & Camps-Valls. Environmental Research Letters., 2022

“Kernel Dependence Regularizers and Gaussian Processes with application to Algorithmic Fairness” Zhu Li, Perez-Suay, Camps-Valls and Sejdinovic, Pattern Rec. 2022

B- Fair optimization

- ML minimizing errors & predictions independent of human factors

$$\text{FairLoss} = \text{Cost}(y, \hat{y}) + \lambda_1 \|w\|_2^2 + \gamma I(\hat{y}, s)$$

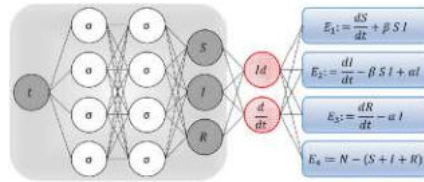
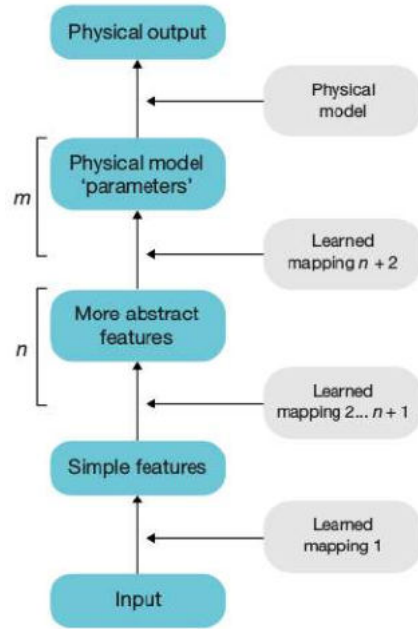


“Fair Kernel Learning” Perez, Laparra, Gomez, Camps-Valls, G. ECML, 2017.

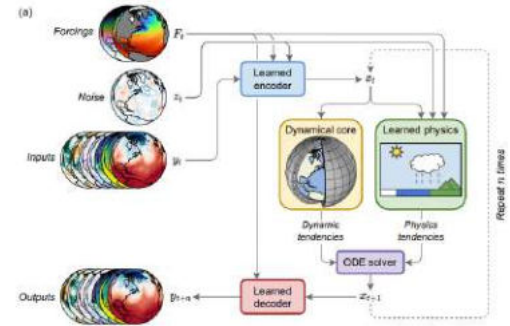
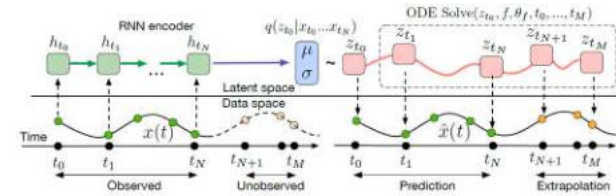
“Consistent Regression of Biophysical Parameters with Kernel Methods” Díaz, Pérez-Suay, Laparra, Camps-Valls, IGARSS 2018

“Kernel Dependence Regularizers and Gaussian Processes with application to Algorithmic Fairness” Zhu Li, Perez-Suay, Camps-Valls and Sejdinovic, , Pattern Rec. 2022

B- Hybrid neural networks



PINNs
 ...
 NeuralODE
 NeuralGCM



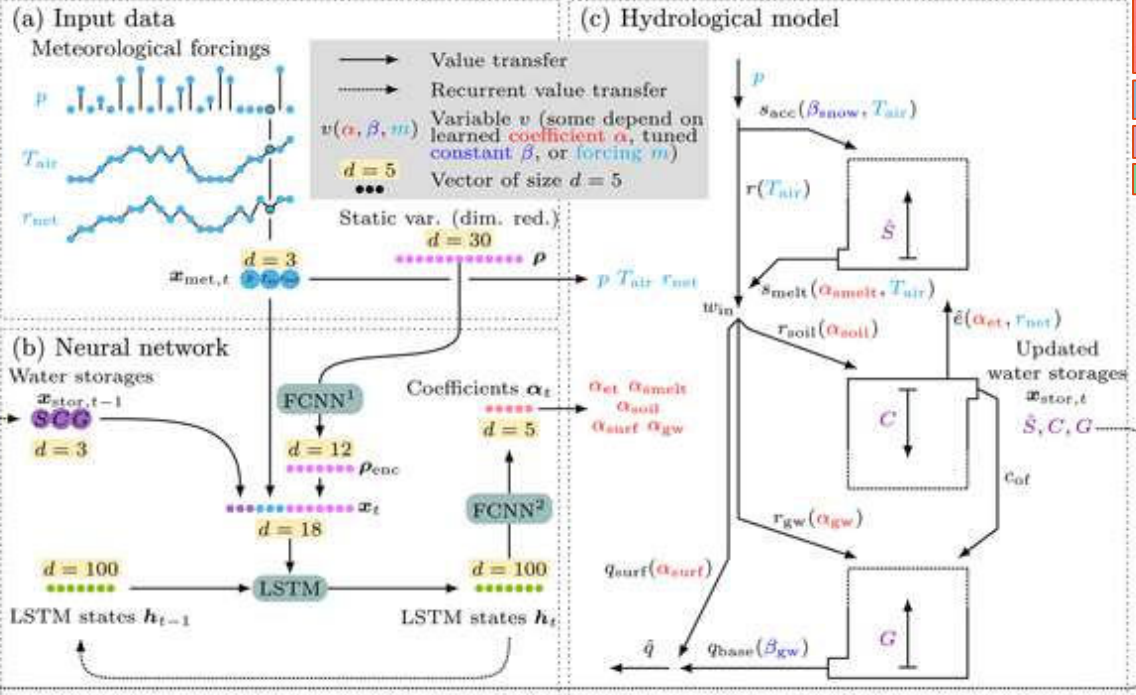
“Deep learning and process understanding for data-driven Earth System Science”, Reichstein, Camps-Valls et al. Nature, 2019.

“Physics-informed neural networks: A deep learning framework for solving forward and inverse problems involving nonlinear partial differential equations.” Raissi, Maziar, Paris Perdikaris, and George E. Karniadakis. Journal of Computational Physics 378 (2019): 686-707.

“Neural ordinary differential equations.” Chen, Ricky TQ, et al. NeurIPS 31 (2018).

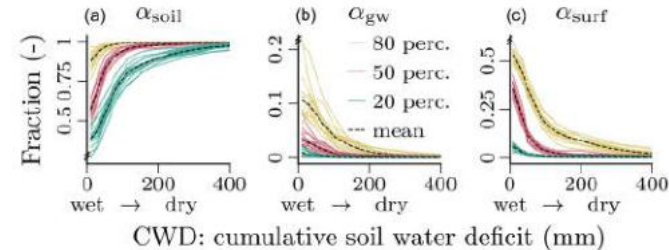
“Neural General Circulation Models.” Kochkov, Dmitrii, et al. arXiv preprint arXiv:2311.07222 (2023).

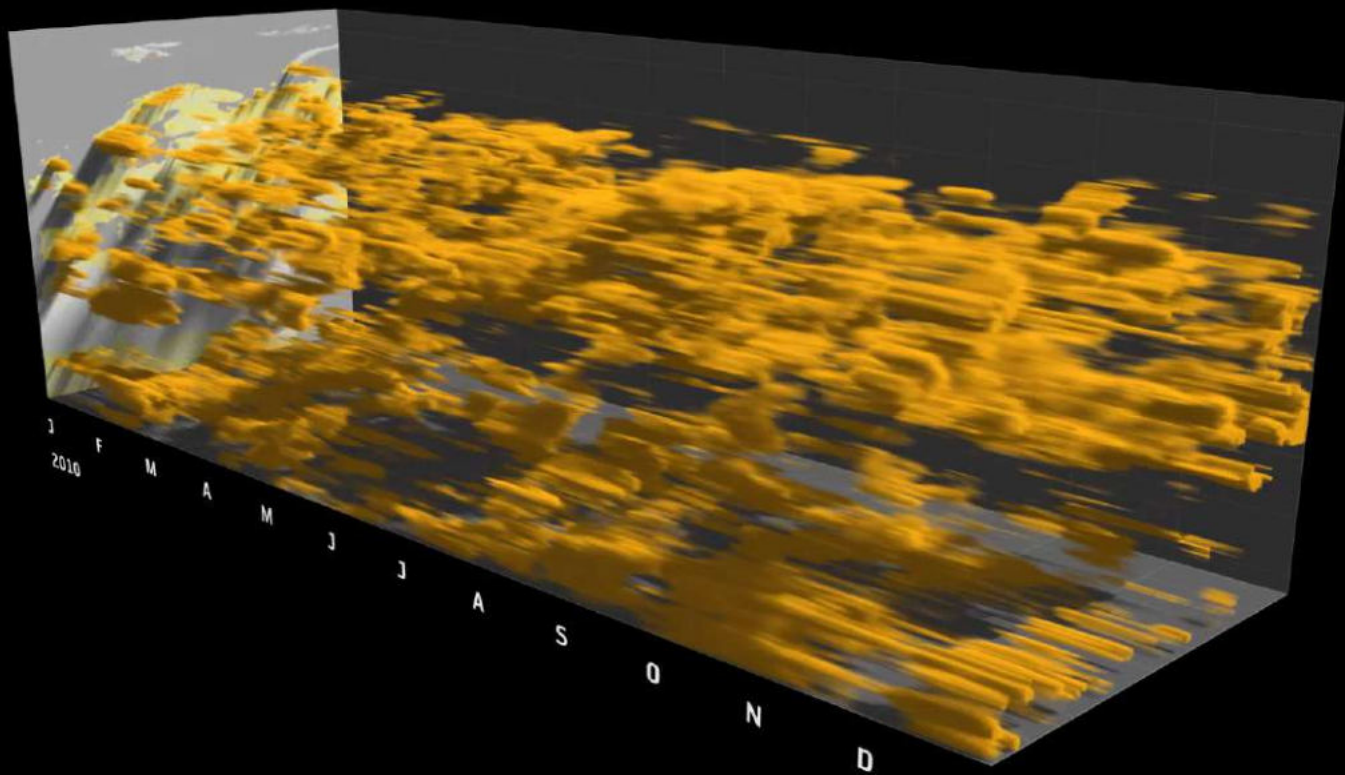
B- Hybrid model for the global hydrological cycle



α_{soil} – soil recharge fraction; α_{gw} – groundwater recharge fraction;
 α_{surf} – surface runoff fraction; α_{smelt} – snowmelt coefficient
 β_{snow} – snow undercatch correction constant; β_{gw} : baseflow constant
 \hat{S} – snow water equivalent; C – cumulative soil water deficit; G – groundwater
 \hat{q} – total runoff. \hat{e} – evapotranspiration

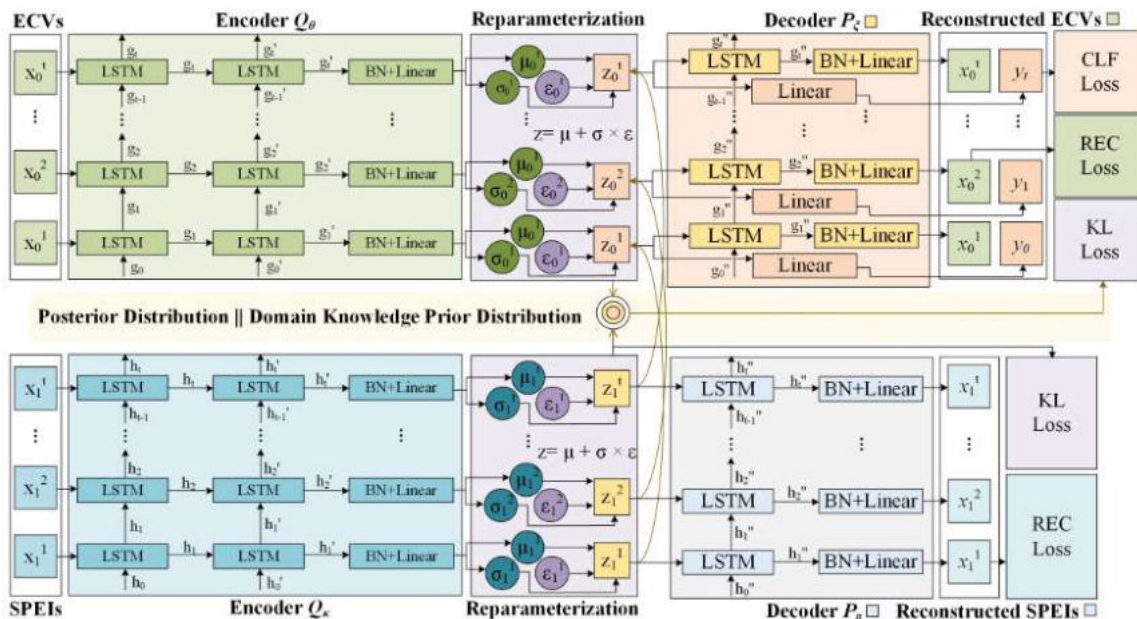
Metric	TWS			SWE			ET		Q			
	MSC	IAV		MSC	IAV		MSC	IAV	MSC	IAV		
Global performance												
NSE (-)	0.84	0.93	0.54	0.96	0.96	0.22	0.96	0.96	-0.11	0.75	0.78	0.47
Pearson's r (-)	0.94	0.97	0.80	0.98	0.98	0.87	1.00	1.00	0.67	0.93	0.97	0.81
SDR (-)	1.15	1.10	1.09	1.02	1.01	1.57	0.99	0.99	1.41	0.93	0.87	1.13
RMSE (mm)	7.33	4.97	3.27	5.22	5.98	2.16	0.07	0.07	0.02	0.06	0.05	0.03
Local performance												
NSE (-)	0.54	0.70	0.26	0.58	0.74	0.15	0.79	0.87	-0.77	0.20	0.17	0.07
Pearson's r (-)	0.82	0.93	0.67	0.89	0.96	0.64	0.95	0.98	0.60	0.80	0.91	0.62
SDR (-)	0.98	1.09	0.95	0.91	0.92	0.97	1.03	1.01	1.65	0.98	0.97	1.04
RMSE (mm)	42.80	22.59	28.72	15.49	13.13	10.60	0.27	0.22	0.14	0.44	0.31	0.27





C- Extreme event detection, anticipation & explanation

- Multimodal architecture: blend&match latent representations

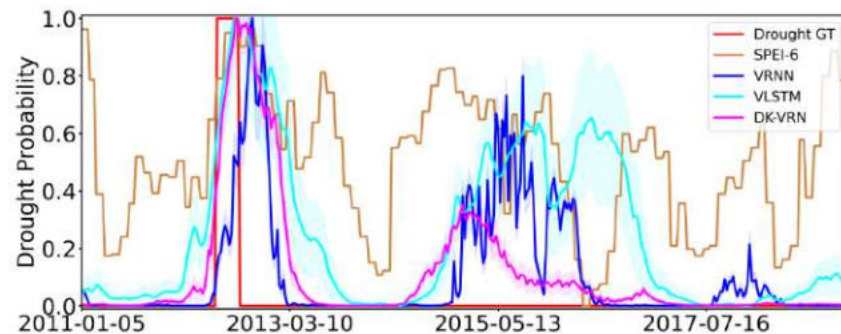


“Domain Knowledge-Driven Variational Recurrent Networks for Drought Monitoring”
 Mengxue Zhang, Miguel Ángel Fernández-Torres, Gustau Camps-Valls, Submitted 2023

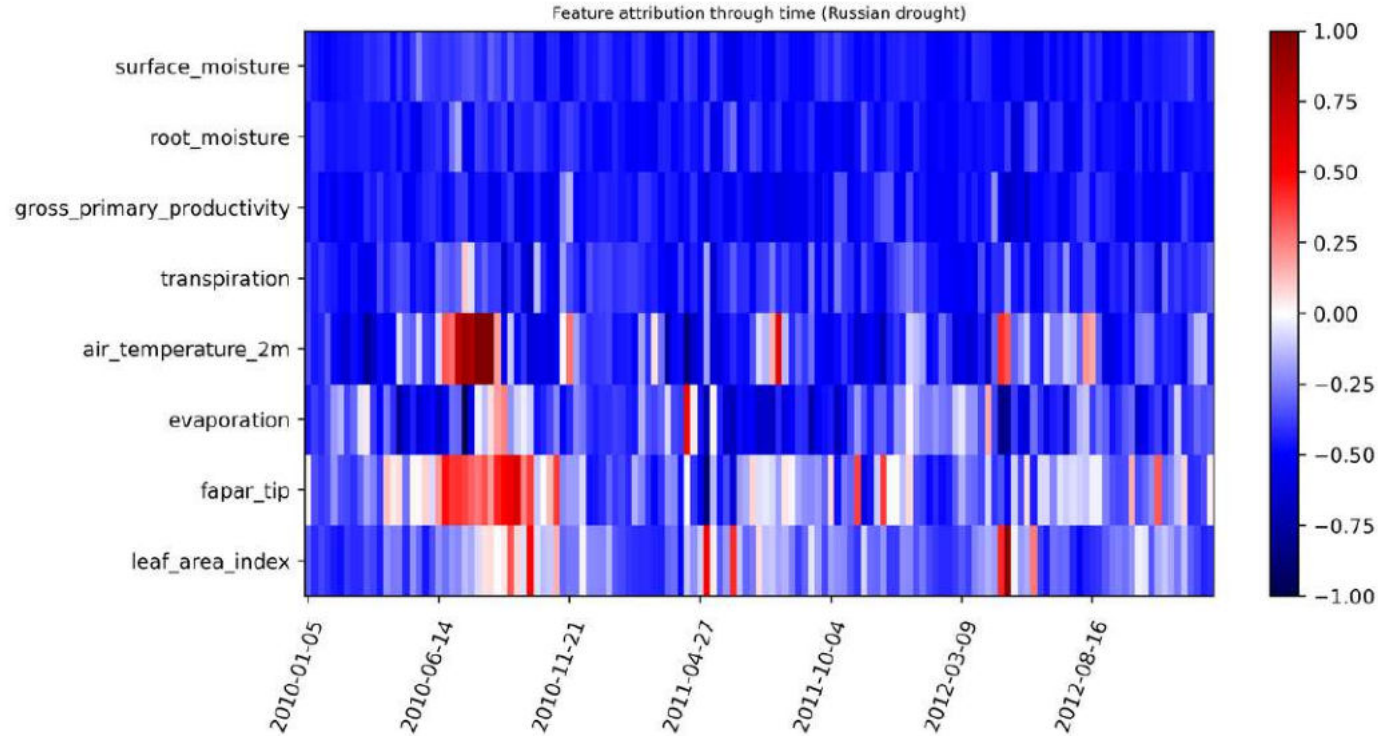
C- Extreme event detection, anticipation & explanation

● Transfer across space and time

	CLF-Loss	REC-Loss	KL-Loss	ROC-AUC	PR-AUC	Macro F1
Afghanistan	✓	✗	standard	71.6±5.3	18.7±4.7	51.2±2.1
	✓	✗	domain knowledge	77.0±4.3	26.1±3.9	53.5±3.0
	✓	✓	standard	73.4±2.9	19.9±3.5	49.3±3.1
	✓	✓	domain knowledge	79.7±0.5	26.4±1.3	53.5±0.7
Italy	✓	✗	standard	68.5±7.2	15.8±6.5	54.4±4.0
	✓	✗	domain knowledge	74.7±8.3	15.9±9.6	56.7±5.1
	✓	✓	standard	76.0±5.1	12.1±2.6	52.1±1.9
	✓	✓	domain knowledge	84.3±0.6	24.2±2.4	55.1±1.1
Moldova	✓	✗	standard	97.1±3.3	28.6±3.0	59.1±9.1
	✓	✗	domain knowledge	98.2±3.1	41.1±7.2	75.9±9.5
	✓	✓	standard	92.1±9.4	21.5±8.5	64.6±1.1
	✓	✓	domain knowledge	94.6±1.1	43.0±4.0	71.5±0.4
Russia	✓	✗	standard	80.6±2.8	14.3±2.7	57.6±1.0
	✓	✗	domain knowledge	82.5±2.7	13.7±0.0	57.4±2.3
	✓	✓	standard	86.0±3.0	17.7±2.8	60.5±1.6
	✓	✓	domain knowledge	89.4±0.2	18.5±0.4	63.2±0.2
Europe-0	✓	✗	standard	74.8±3.5	13.2±0.9	56.2±1.0
	✓	✗	domain knowledge	80.2±3.2	14.4±3.9	58.0±1.9
	✓	✓	standard	79.6±0.9	16.7±1.3	58.1±1.0
	✓	✓	domain knowledge	84.3±0.1	17.4±0.3	61.1±0.3
Europe-1	✓	✗	standard	70.9±5.5	0.5±0.2	48.8±1.6
	✓	✗	domain knowledge	76.9±4.7	0.5±0.2	48.4±0.7
	✓	✓	standard	76.5±5.0	0.4±0.1	49.2±0.9
	✓	✓	domain knowledge	82.8±0.4	0.7±0.1	50.2±0.1

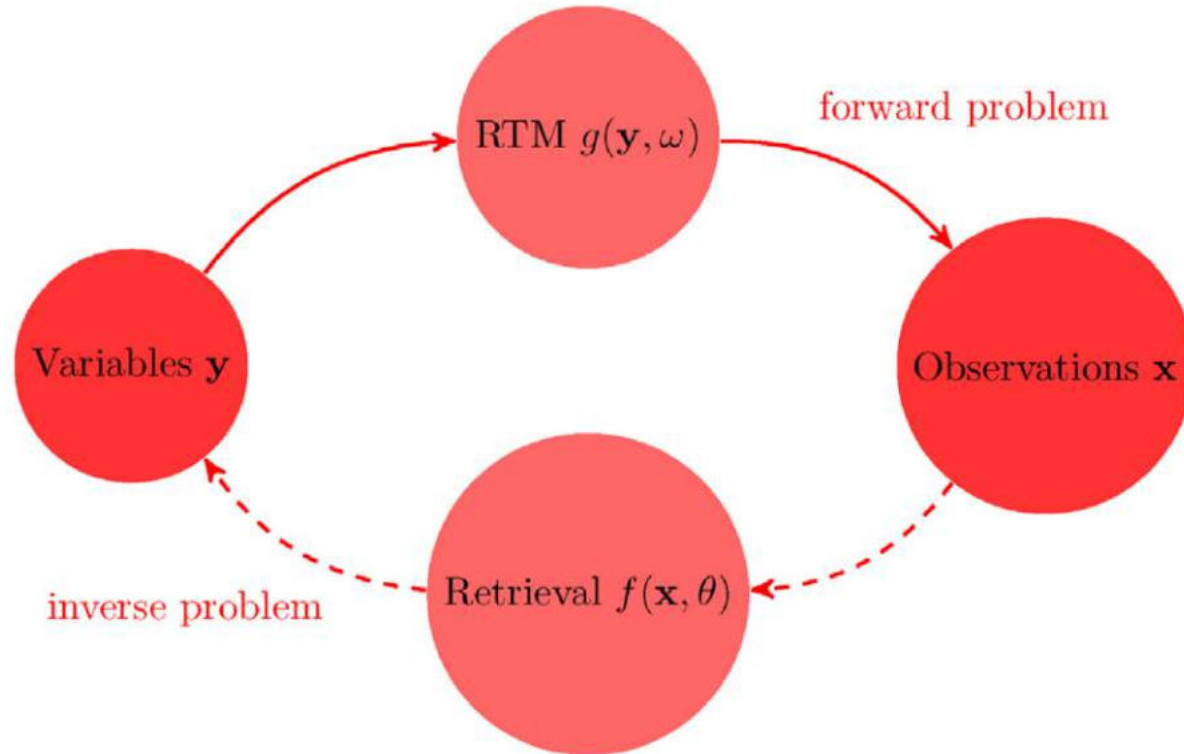


C- Extreme event detection, anticipation & attribution



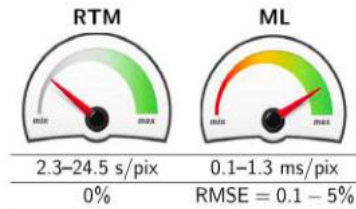
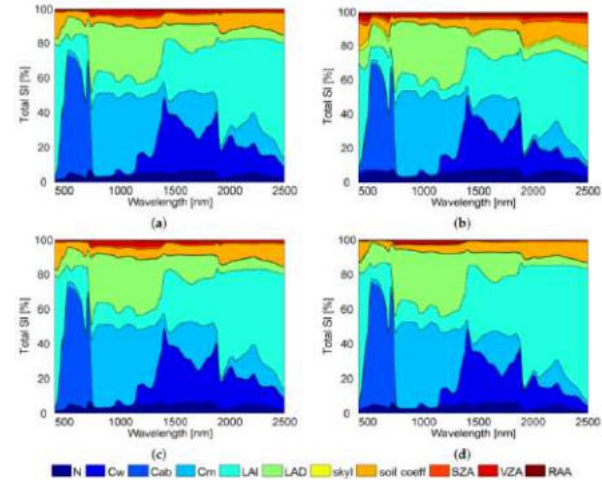
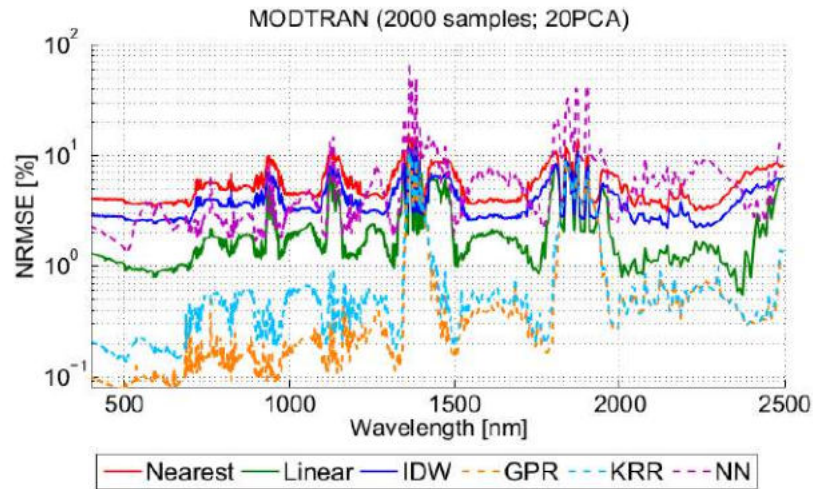
2. Emulation

Forward & inverse modeling



A- Emulating complex codes

- GP Emulation = UQ/UP + Sensitivity analysis + Speed



“Emulation of Leaf, Canopy and Atmosphere Radiative Transfer Models for Fast Global Sensitivity Analysis”

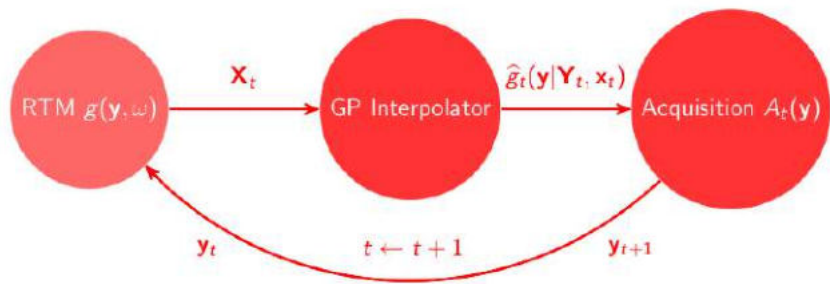
Verrelst, Camps-Valls et al Remote Sensing of Environment, 2016

“Emulation as an accurate alternative to interpolation in sampling radiative transfer codes”

Vicent and Camps-Valls, IEEE Journal Sel. Topics Rem. Sens, Apps. 2018

B- Optimizing emulators with GPs

- AGAPE = GP interpolation + Acquisition function

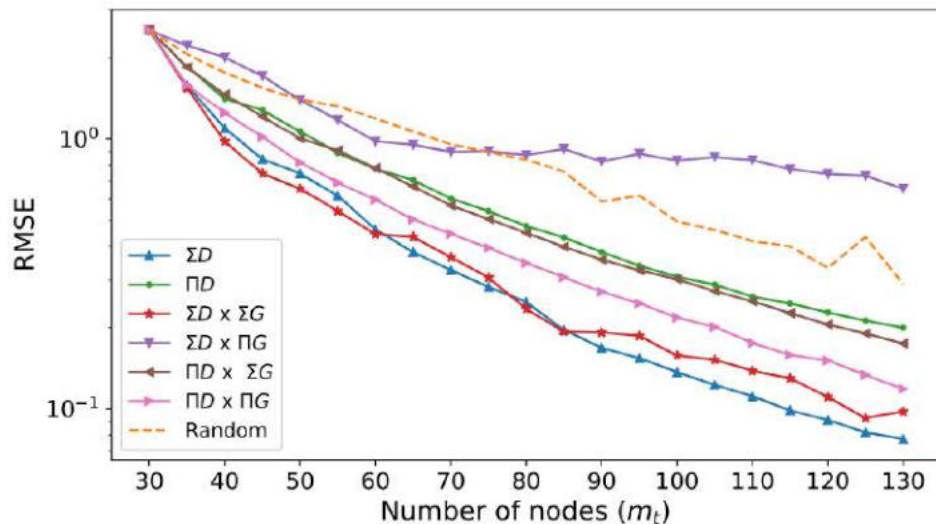


$$\hat{g}(\mathbf{y}|\mathbf{Y}_t, \mathbf{x}_t) = \mu_{\text{GP}}(\mathbf{y}) = \mathbf{k}^\top \mathbf{K}^{-1} \mathbf{x}_t$$

$$A_t(\mathbf{y}) = [G_t(\mathbf{y})]^{\beta_t} D_t(\mathbf{y}), \quad \beta_t \in [0, 1]$$

$$D_t(\mathbf{y}) = \sigma_{\text{GP}}^2(\mathbf{y}) = k(\mathbf{y}, \mathbf{y}) - \mathbf{k}^\top \mathbf{K}^{-1} \mathbf{k}$$

$$G_t(\mathbf{y}) = \|\nabla \hat{g}(\mathbf{y}|\mathbf{Y}_t, \mathbf{x}_t)\| = \left\| \sum_{i=1}^{m_t} \alpha_i \nabla k(\mathbf{y}, \mathbf{y}_i) \right\|$$



3. Learning Parametrizations

Model inversion and learning parametrizations

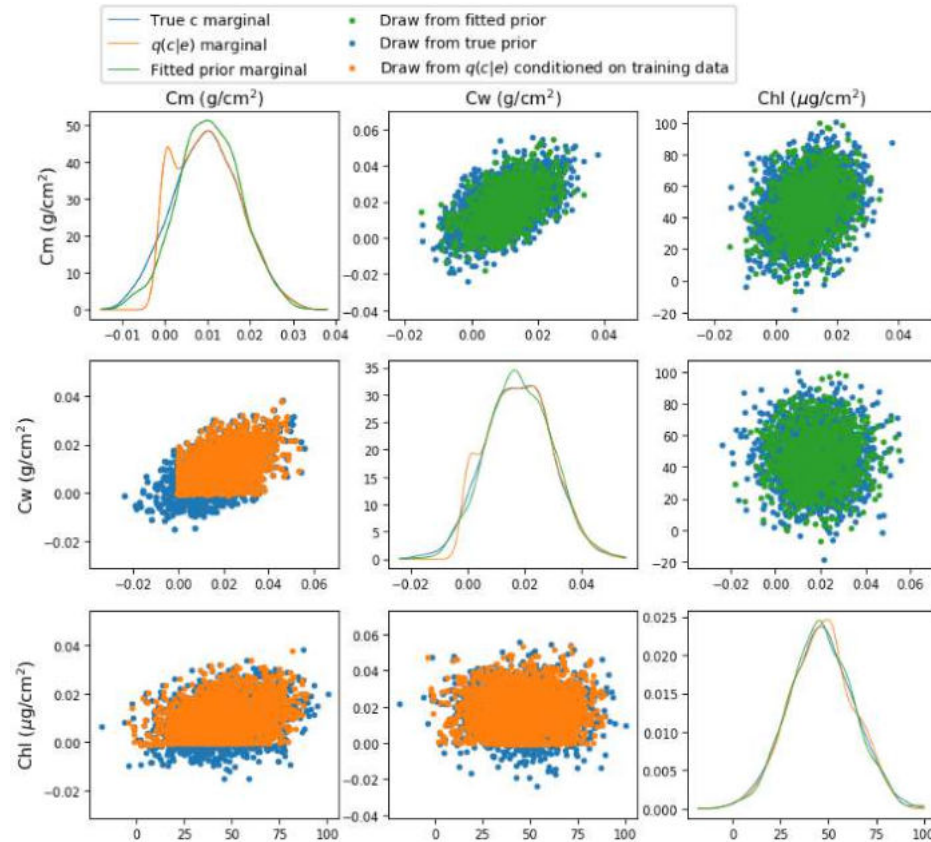
- *RTM* is a deterministic model mapping params (c) to radiances (E)
- Assume a Gaussian prior $P(c) = \mathcal{N}(\mu_\phi, \Sigma_\phi)$
- The likelihood is hard to integrate w/ *RTM* inside the Gaussian mean!

$$P(E|c) = \mathcal{N}(E|RTM(c), \sigma I)$$

- Kingma and Welling (2013)
 - Introduce the variational posterior into the log marginal likelihood
 - Choose the variational posterior to be Gaussian (mean&cov w/ nnet)
 - Compute the expected value of the log-likelihood (KLDs btw. Gaussians easy)
- Unlike in the VAE literature: deterministic decoder + low noise variance in the lik.

Model inversion and learning parametrizations

- VAE is orders of magnitude faster than MCMC or ABC, but problems with multimodal distributions
- The VAE scheme provides a posterior approximation
- Readily used for fast inverse modeling & parameterization
- Learn prior distributions of land parameters; canopy water content, chlorophyll and dry matter



“Variational inference over radiative transfer model for biophysical parameter retrieval”

D. Svendsen, L. Martino, V. Laparra, G. Camps-Valls, *Machine Learning*, 2021

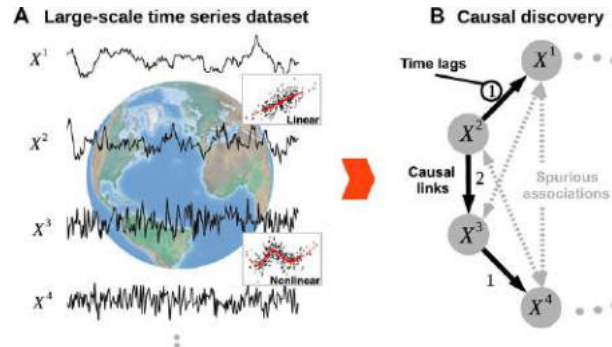
Part III

Causal Machine Learning

Pragmatic approaches in the wild

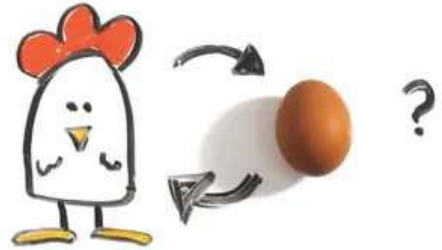
Causal understanding *means* better management & robustness

- **Discover causal relations** → being right for the right reasons
- **Identify causal factors** of events → prevent them from occurring
- **Predict occurrence** of disasters → causal forecasting models
- **Evaluate the effectiveness of interventions** → better policies
- **Causal evaluation** → hypothesis testing & model-obs comparison



Challenges in causality

1. Difficulty of identifying causation from data
2. Multidimensionality & collinearity
3. Poor data quality & assumptions (lin/Gauss/iid)
4. Poor data quantity
5. Many factors difficult to measure or quantify
6. Many confounders & sufficiency assumption
7. Hidden/latent factors
8. Nonstationarities in a changing Planet
9. Identifiability and falsifiability issues
10. Weak or controversial domain knowledge



1. Causal discovery in time series

Causal inference for the Earth system



PERSPECTIVE

<https://doi.org/10.1038/s41467-019-10105-3>

OPEN

Inferring causation from time series in Earth system sciences

Jakob Runge^{1,2}, Sebastian Bathiany^{3,4}, Erik Bollt⁵, Gustau Camps-Valls⁶, Dim Coumou^{7,8}, Ethan Deyle⁹, Clark Glymour¹⁰, Marlene Kretschmer⁸, Miguel D. Mahecha¹¹, Jordi Muñoz-Marró⁶, Egbert H. van Nes⁴, Jonas Peters¹², Rick Quax^{13,14}, Markus Reichstein¹¹, Marten Scheffer⁴, Bernhard Schölkopf¹⁵, Peter Spirtes¹⁰, George Sugihara⁹, Jie Sun^{5,16}, Kun Zhang¹⁰ & Jakob Zscheischler^{17,18,19}

IEEE TRANSACTIONS ON GEOSCIENCE AND REMOTE SENSING

Causal Inference in Geoscience and Remote Sensing From Observational Data

Adrián Pérez-Suay¹, Member, IEEE, and Gustau Camps-Valls², Fellow, IEEE

Abstract—Establishing causal relations between random variables from observational data is perhaps the most important challenge in today's science. In remote sensing and geosciences, this is of special relevance to better understand the earth's system and the complex interactions between the governing processes.

with societal, economical, and environmental challenges, such as climate change [2], [3]. There is an urgent need for tools that help us to observe and study the earth system. Nowadays, machine learning and signal processing play a crucial role in



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Discovering causal relations and equations from data

Gustau Camps-Valls^{a,*}, Andreas Gerhardus^{b,1}, Urmi Ninad^{c,b,1}, Gherardo Varando^{a,1}, Georg Martius^{d,e}, Emili Balaguer-Ballester^{f,g}, Ricardo Vinuesa^h, Emiliano Diaz^a, Laure Zannaⁱ, Jakob Runge^{b,c}



nature reviews earth & environment

<https://doi.org/10.1038/s43017-023-00431-y>

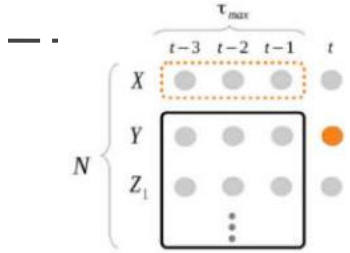
Technical review

Check for updates

Causal inference for time series

Jakob Runge^{1,2}, Andreas Gerhardus¹, Gherardo Varando³, Veronika Eyring^{4,5} & Gustau Camps-Valls²

Ex. 1 - Nonlinear Nonstationary Granger Causality (XKGC)



$$Y_{t+1} = a^T X_t + \varepsilon_t^Y$$

$$Y_{t+1} = b_1^T Y_t + b_2^T X_t + \varepsilon_t^{Y|X}$$

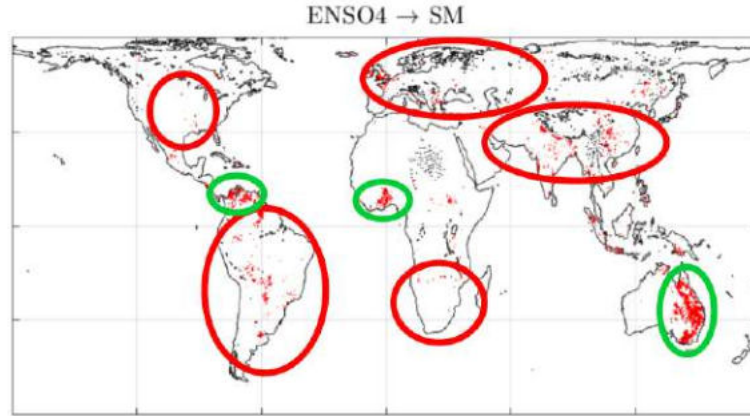
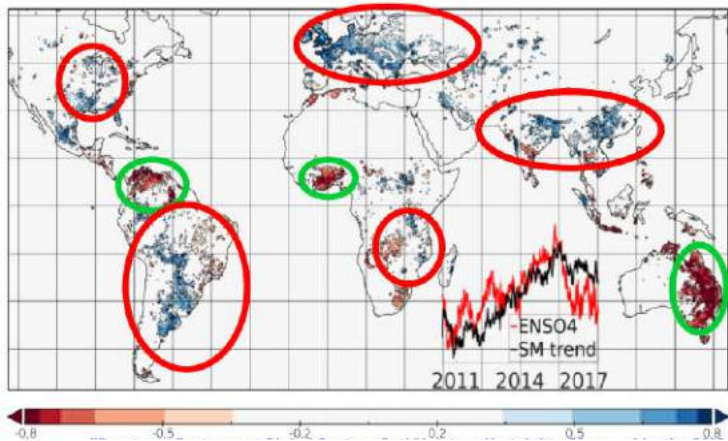
$$X \rightarrow Y \leftrightarrow \mathbb{V}[\varepsilon_t^Y] \ll \mathbb{V}[\varepsilon_t^{Y|X}]$$



$$a_H = (K(X_t, X'_t) + \varepsilon_t^Y)^{-1} Y_{t+1}$$

$$b_H = (L([Y_t, X_t], [Y'_t, X'_t]) + \varepsilon_t^{Y|X})^{-1} Y_{t+1}$$

$$X \rightarrow Y \leftrightarrow \mathbb{V}_H[\varepsilon_t^Y] \ll \mathbb{V}_H[\varepsilon_t^{Y|X}]$$



- Causality is sharper than correlation
- ENSO4 “causes” SM in very dry (Sahel) and very wet (tropical rain forests)

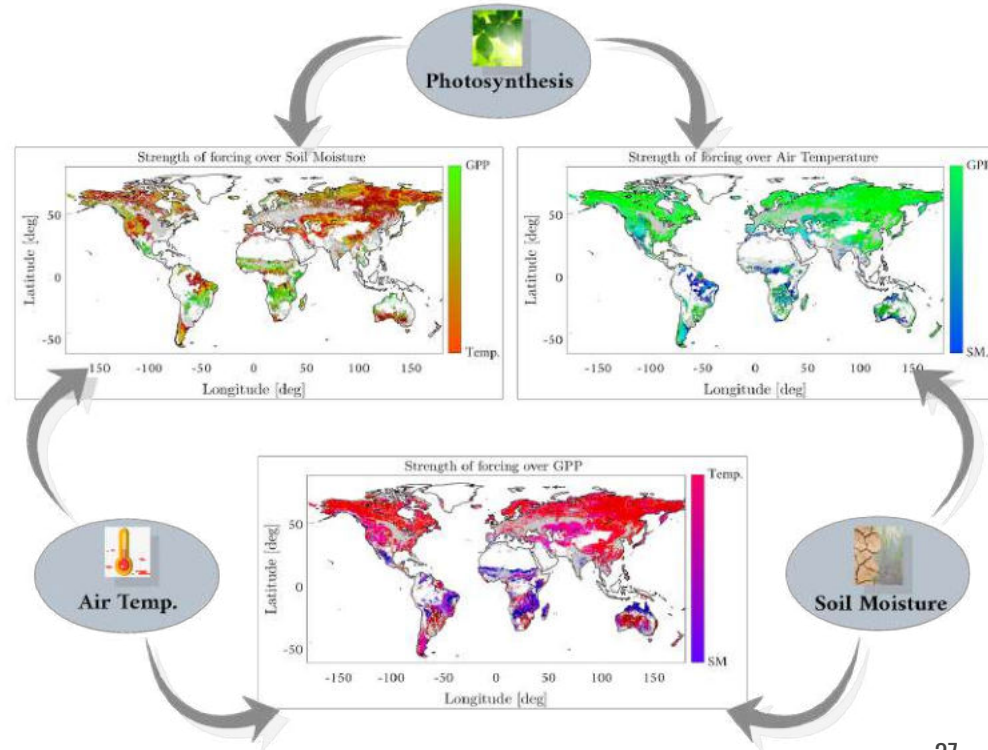
“Inferring causation from time series with perspectives in Earth system sciences”, Runge, Bathiany, Bollt, Camps-Valls, et al. Nat Comm (submitted), 2018.

“Causal Inference in Geoscience and Remote Sensing from Observational Data,” Pérez-Suay and Camps-Valls, IEEE Trans. Geosc. Rem. Sens, 2018

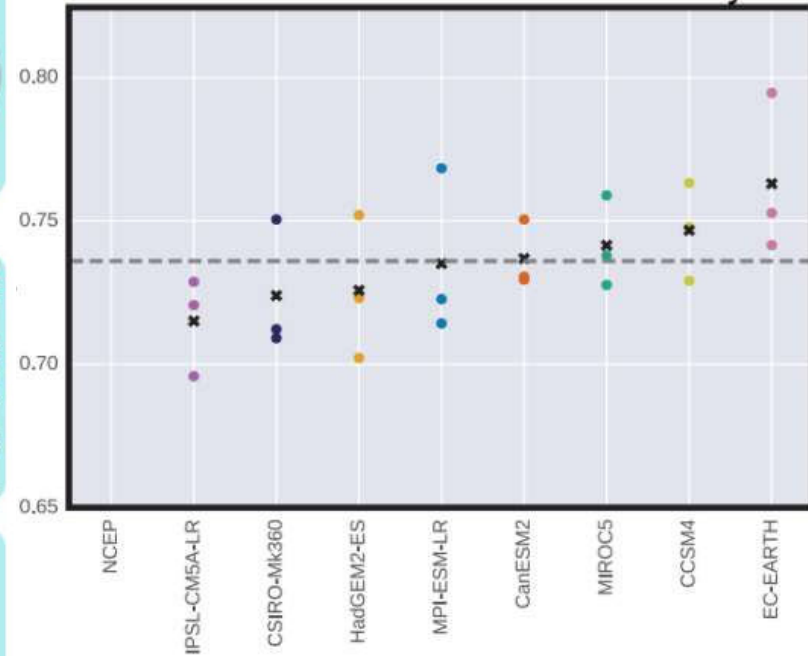
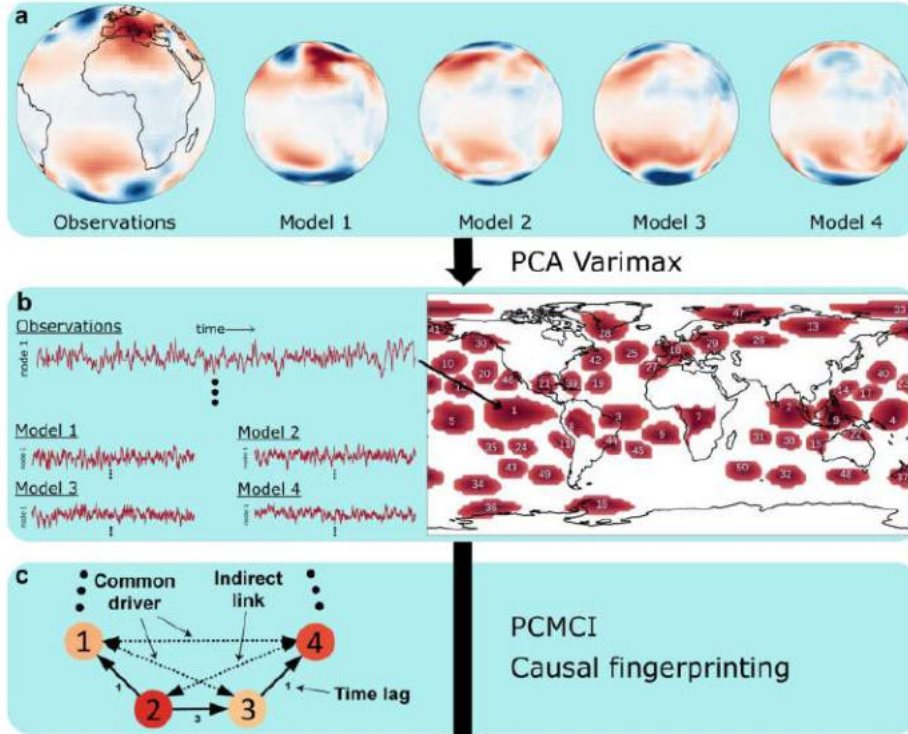
“CauseMe: An online system for benchmarking causal inference methods,” Muñoz-Marí, Runge, Camps-Valls. (2019). CauseMe: <http://causeme.uv.es>

Ex. 2- Robust Convergent Cross Mapping (RCCM)

- Causality on (GPP, Tair, SM)
- Causal maps capture general knowledge
- In dry (water-limited) areas, GPP is caused/driven by SM
- Temperature is mainly an effect in boreal regions
- GPP affects SM in dry/savannas/shrubs, possibly related through ET
- SM in boreal regions matches with a reduction in radiation and temperature



Ex. 3- PC with momentary conditional independence (PCMCI)





CauseMe - A platform to x +



🔒 127.0.0.1:5000/run_methods/



⏏

I



Read 127.0.0.1

2. Learning causal representations

Learning causal feature representations

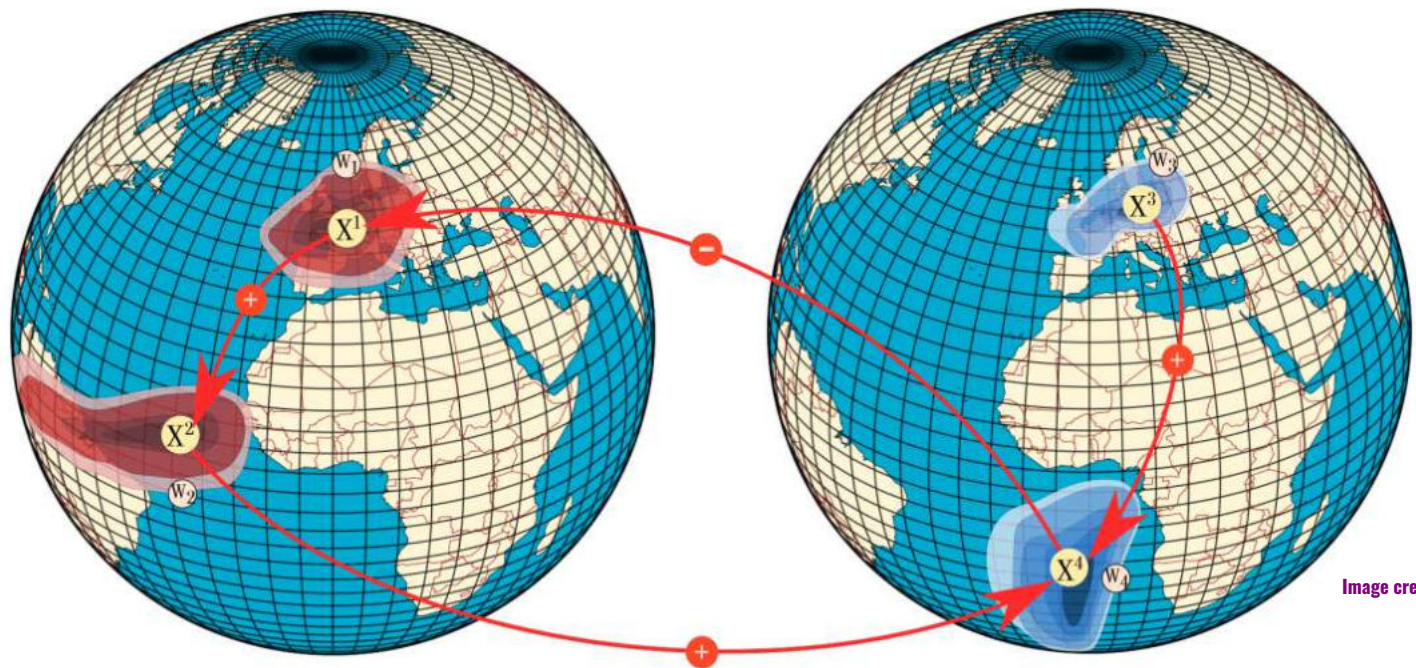
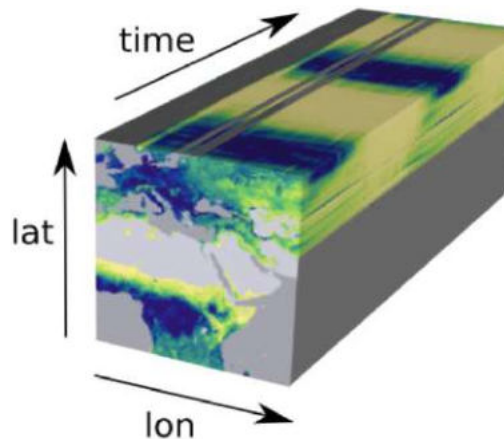
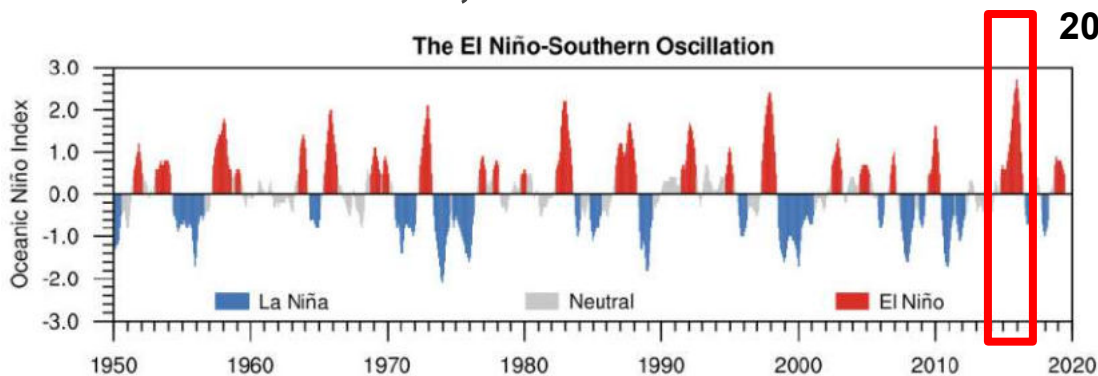


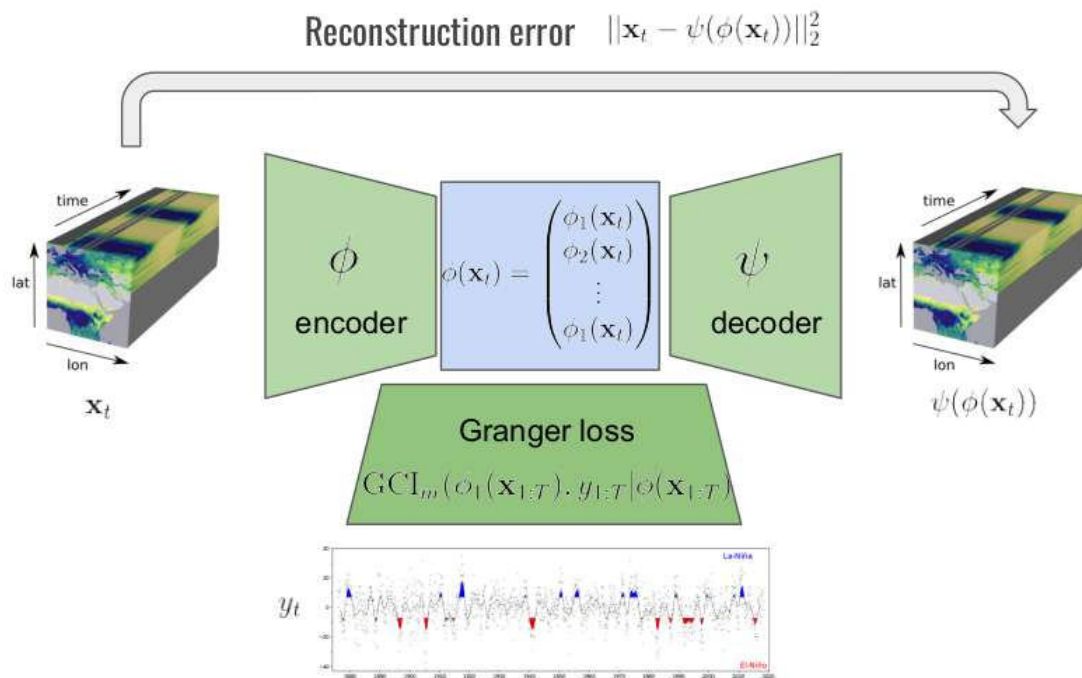
Image credits: Jakob Runge, 2019

Learning causal feature representations

- ENSO influences moisture, greenness & precipitation spatio-temp patterns
- Goal: Learn causal impact teleconnections of ENSO on greenness
- NDVI from MODIS in Africa, linear interp, anomalies
- ENSO3.4 index, focus on 2014-2017



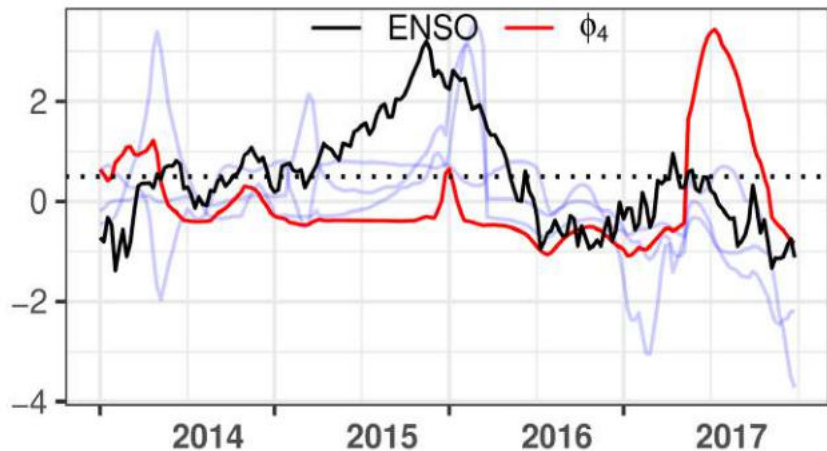
Learning causal feature representations



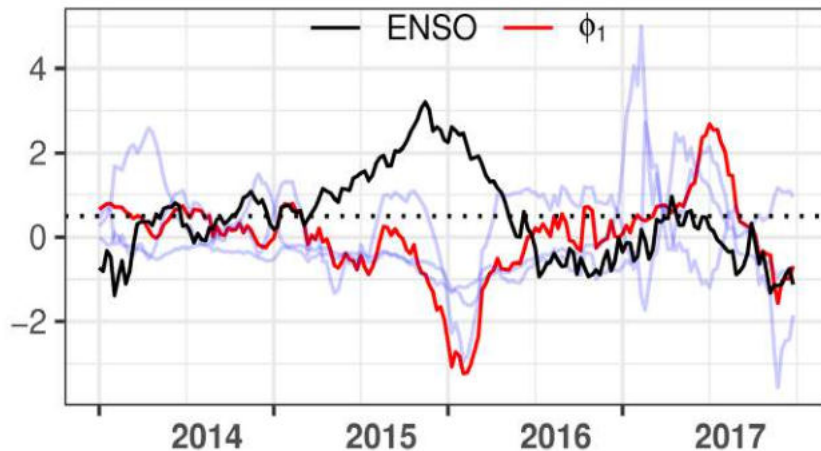
$$\frac{1}{T} \sum_{t=1}^T \|\mathbf{x}_t - \psi(\phi(\mathbf{x}_t))\|_2^2 - \beta GCI_m(\phi_1(\mathbf{x}_{1:T}), y_{1:T} | \phi(\mathbf{x}_{1:T}))$$

Learning causal feature representations

No Granger penalization $\beta = 0$



Granger penalization $\beta = 0.01$

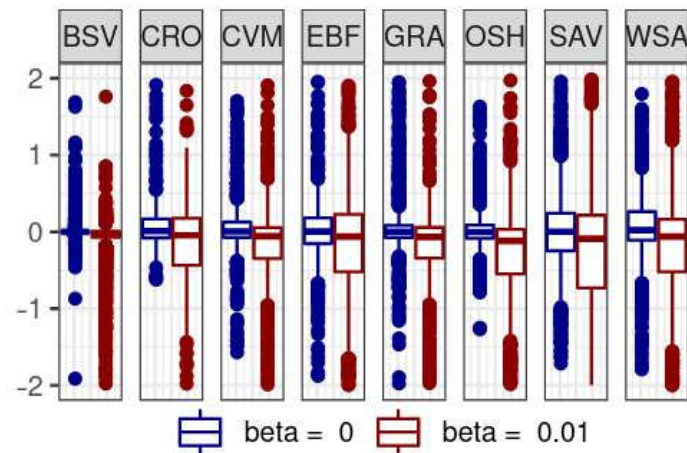
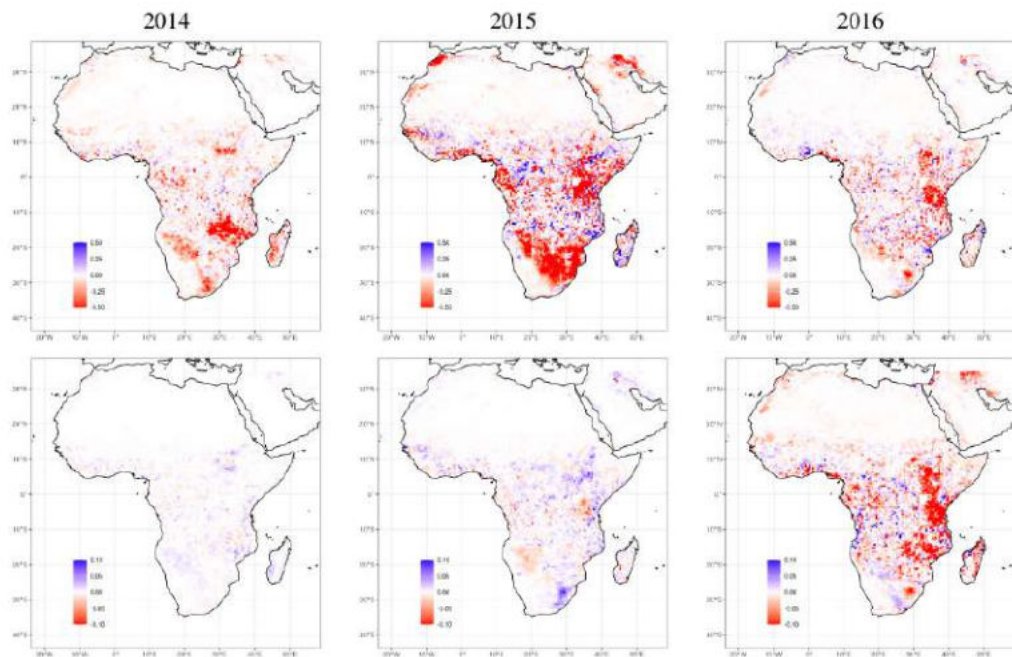


Learning causal feature representations

- XAI (integrated gradients) on the Granger Autoencoder
- Spatio-temporal explicit attributions

$\beta = 0.01$

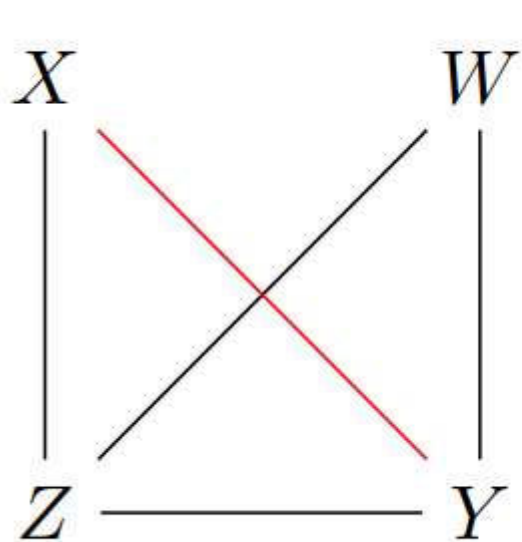
$\beta = 0$



3. Causal discovery with LLMs

Large Language Models for Constrained-Based Causal Discovery

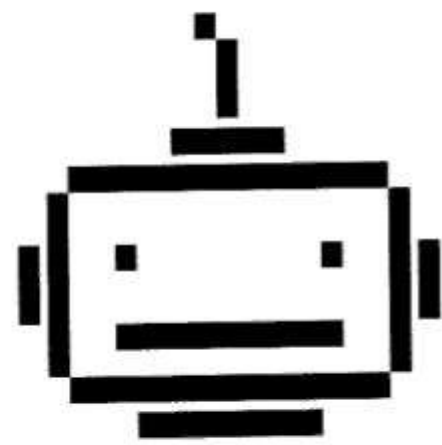
.....



$X \perp\!\!\!\perp Y | Z?$



YES



Large Language Models for Constrained-Based Causal Discovery

Persona specification
Instructions
Context
Variables description
CI Statement question
Response template

```
system: You are a helpful expert in {field}  
and willing to answer questions.
```

```
system: You will be asked to provide your  
best guess and your uncertainty on the  
statistical independence between two  
variables potentially conditioned on a set  
of variables. Your answer should not be  
based on data or observations but on  
available knowledge. Even when unsure or  
uncertain, provide your best guess (YES or  
NO) and the probability that your guess is  
correct. Answer only in the required format.
```

```
user: {context} Consider the following  
variables:  
{variables list and description}  
is {x} independent of {y} given {z}?
```

```
system: Work out the answer in a  
step-by-step way to be as sure as possible  
that you have the right answer. After  
explaining your reasoning, provide the  
answer in the following form: [<ANSWER>  
(<PROBABILITY>)] where ANSWER is either YES  
or NO and PROBABILITY is a percentage  
between 0\% and 100\%.  
YES stands for "{x} is independent of {y}  
given {z}" and NO stands for "{x} is not  
independent of {y} given {z}".
```

```
For example [NO (50%)] or [YES (50%)].
```

**“Large Language
Models for
Constrained-Based
Causal Discovery”** K-
H Cohrs, G. Varando, G.
Camps-Valls, AAAI
2024

Impact on food insecurity

“A total of 6.5 million people face acute food insecurity amid the driest conditions in 40 years(...) A total of 1.84 million children under 5 face acute malnutrition. (...) over 1.5 million drought-driven displacements since the start of the climate crisis.”

World Food Programme, Jan 2023

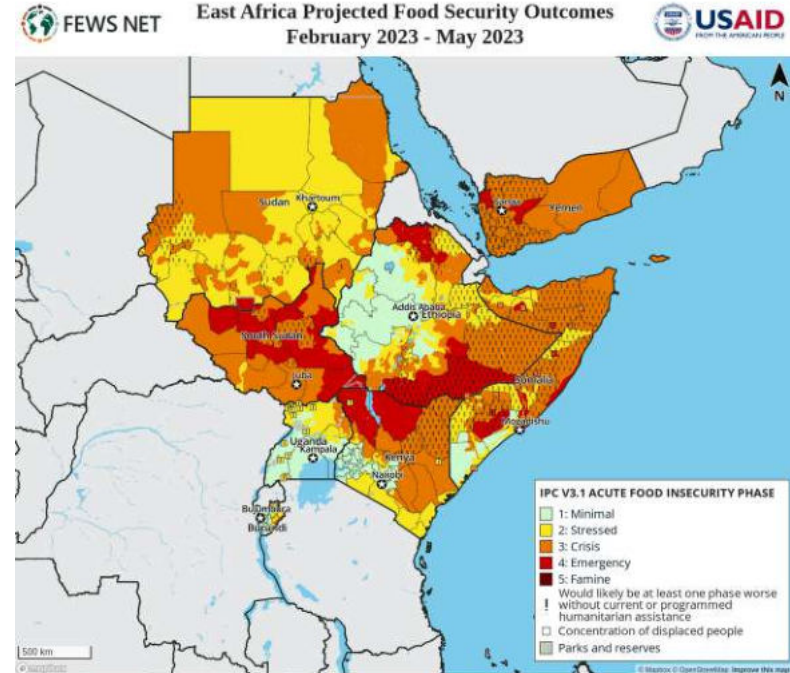
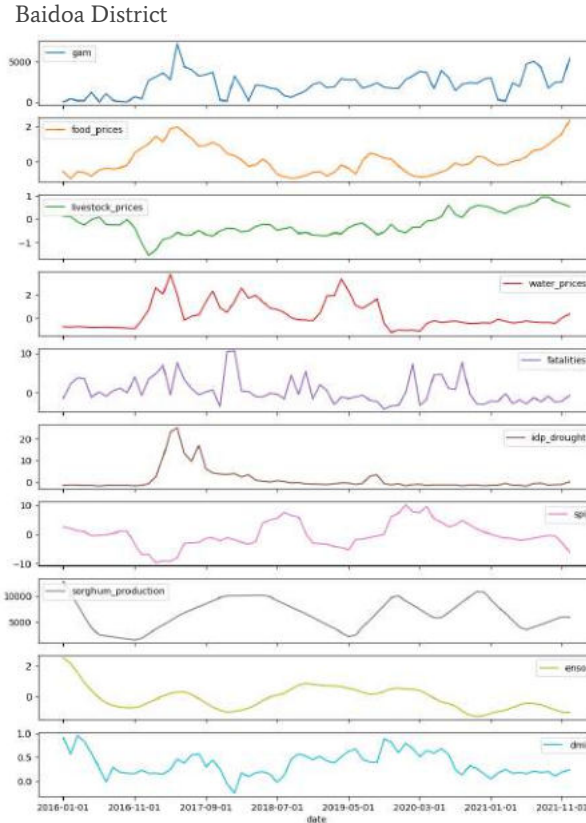


Image credits to: FEWS NET, <https://fews.net>49

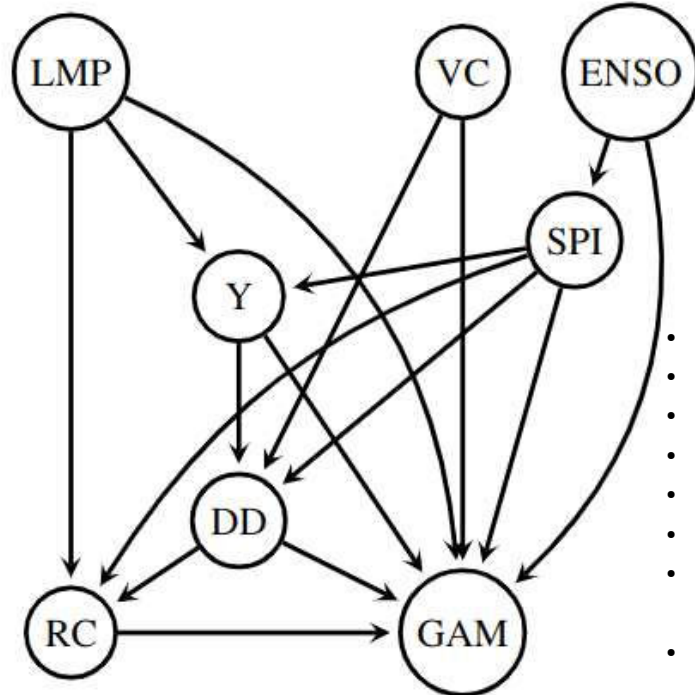
Impact on food insecurity

- Monthly data
- 2016 - 2021
- 37 districts
- N~70
- Market/food/livestock/water prices, displaced people, fatalities, climate variables, humanitarian aid
- Target: malnutrition



Large Language Models for Constrained-Based Causal Discovery

- Find traces of causal reasoning in model's answers
- Promising, alternative avenue for automated causality
- Useful for fast response, scarce data regimes



- El Niño Southern Oscillation (ENSO)
- Standardized Precipitation Index (SPI)
- Fatalities due to conflicts (VC)
- Local market prices (LMP)
- Sorghum yield production (Y)
- Drought-induced IDP (DD)
- People receiving cash from humanitarian aid (RC)
- Global Acute Malnutrition (GAM).

Part IV

Conclusion



Take-home messages

- **Many challenges:** emulate, learn representations, ensure consistency, interpretability, discover causal relations
- **Take 1:** Understanding processes by blending domain knowledge & data
- **Take 2:** Understanding complex systems means answering causal queries

