

Video Summarization

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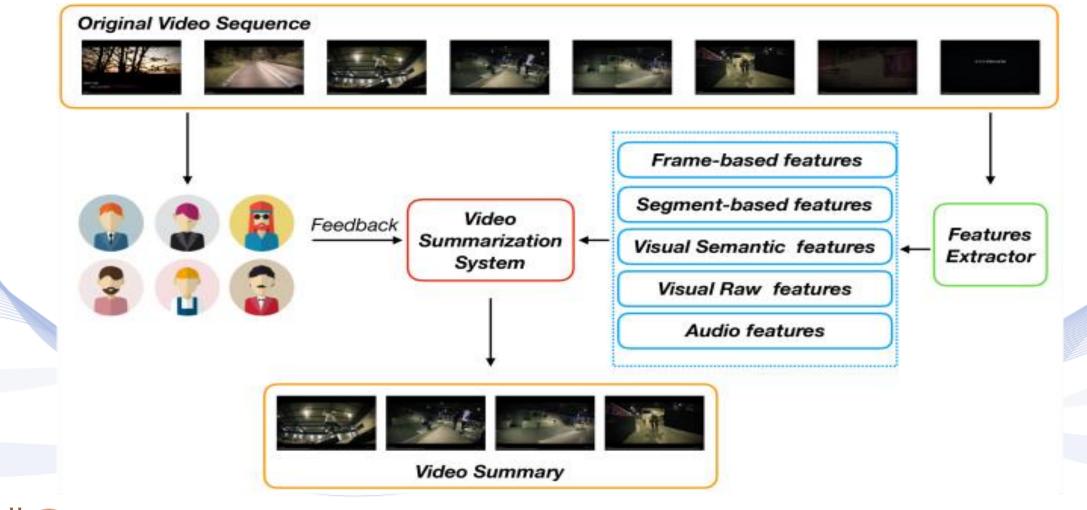


Introduction

- **CML**
- Video summarization is the automated construction of a short version of an original full-length video.
- It is necessary in applications where videos are recorded, stored and accessed in abundance.
 - Video summarization has various applications in several industries (media, surveillance, WWW, etc.).
- **Example**: Users would ideally like to browse quickly through large video databases, to get an idea of the content.



Introduction







- Video summarization algorithms result in a short *summary* of the video.
- The challenge is to automatically select which content will be retained and which will be discarded during the summarization process.
- Only the most informative and/or interesting parts should
 - be kept.



Video summarization use-cases

- Movie trailers
- Advertisement creation
- Sports highlights
- Anomaly detection from video surveillance
- Redundancy removal
- Reduction of computational time, storage requirements
- Data visualization

• Search, Retrieval, Recommendation [WOR2020]

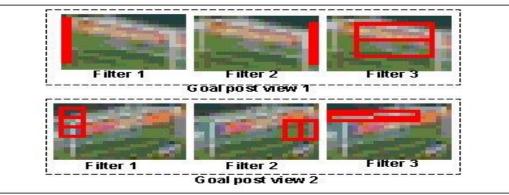
Video summarization use-cases

• Summarization of personal videos [DAR2014]





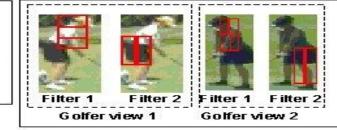
• Sports highlights [ZHA2006]



Soccer Models Interpretation



Catcher Model Interpretation



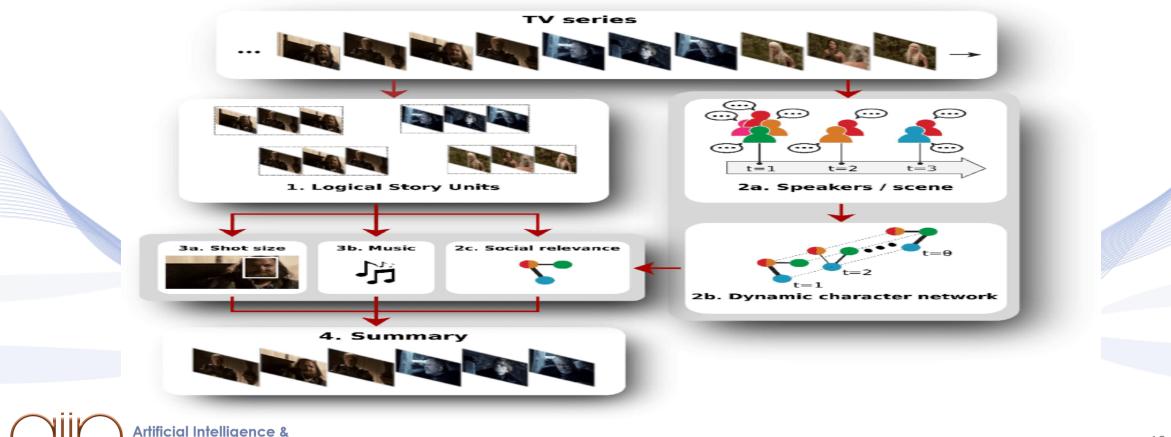
Golf Models Interpretation





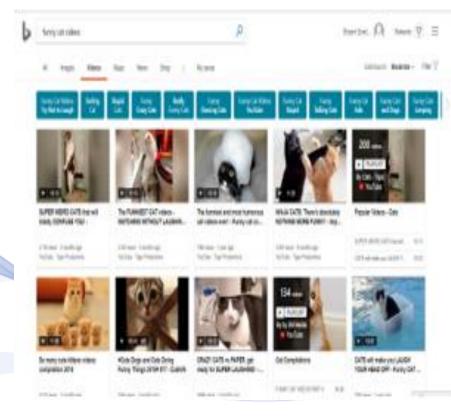
• Automatic TV/film trailers [BOR2018]

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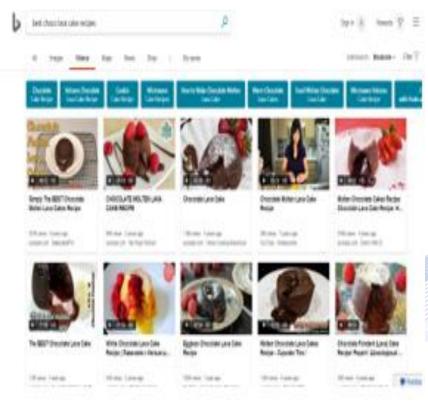


• Video search engines [IRI2010]



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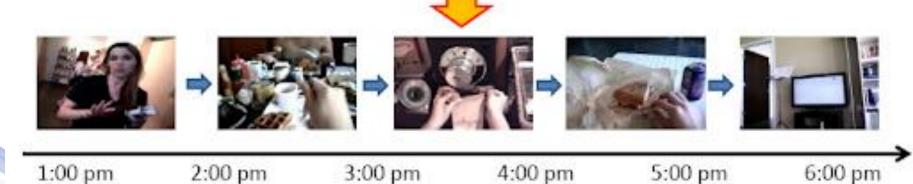






Egocentric Video storyboard

Input: Egocentric video of the camera wearer's day



Output: Storyboard summary of important people and objects

Image from vision.cs.utexas.edu





Medical Video summarization

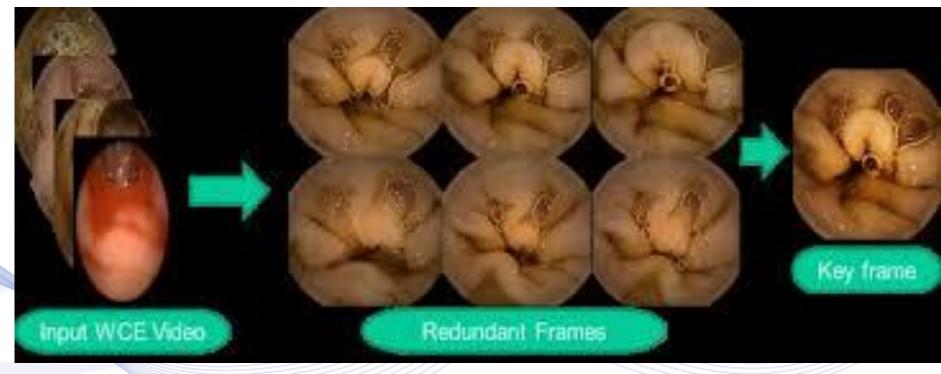


Image from E3S Web of Conferences



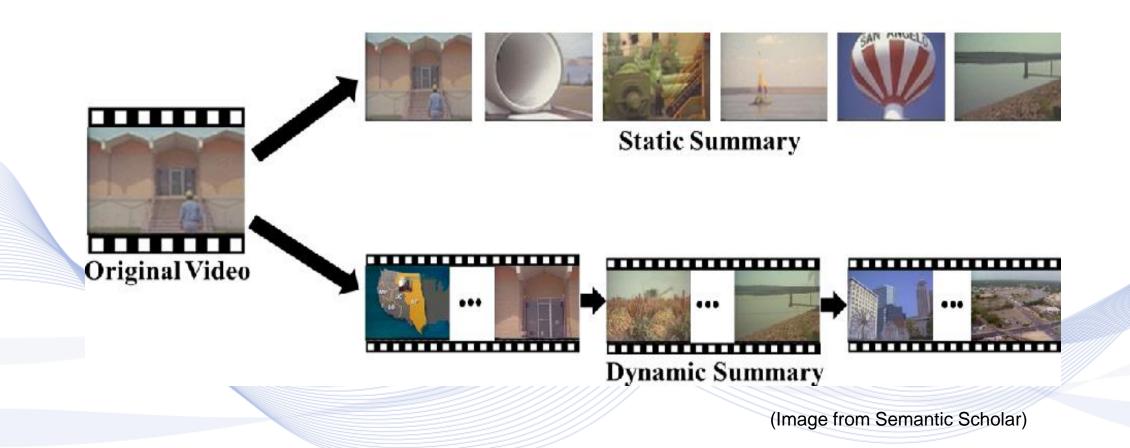
Video summary types

- There are two main types of video summaries: [MAD2016]
 - Static video summaries (storyboard/gallery/key-frame set),
 - **Dynamic video summaries** (skims/trailers).
- A static summary is a temporally ordered set of selected keyframes.
 - A collection of still images.
- A dynamic summary is a temporally ordered set of selected key-segments.



Video summary types









- Several video summarization methods have been developed over the years.
- They can be classified into *four major categories*, based on their properties and characteristics.
 [BUR2020]





- Feature-based summarization [BUR2020]
 - The original video content is represented by an aggregation of various features.
 - These features may capture properties such as visible objects, events, color, motion type, etc.
 - Feature extraction and aggregation is the most important step.
 - A machine learning method (e.g., clustering) processes these features, in order to select only a subset of the original content.



- The selection process may optionally be applied at different levels of detail.
- First, the original video is segmented into scenes and/or shots.
- Then, important key-scenes and/or key-shots are identified and retained, while the remaining ones are discarded.
- Finally, important *key-frames* and/or *key-segments* are identified within each of the selected scenes/shots.

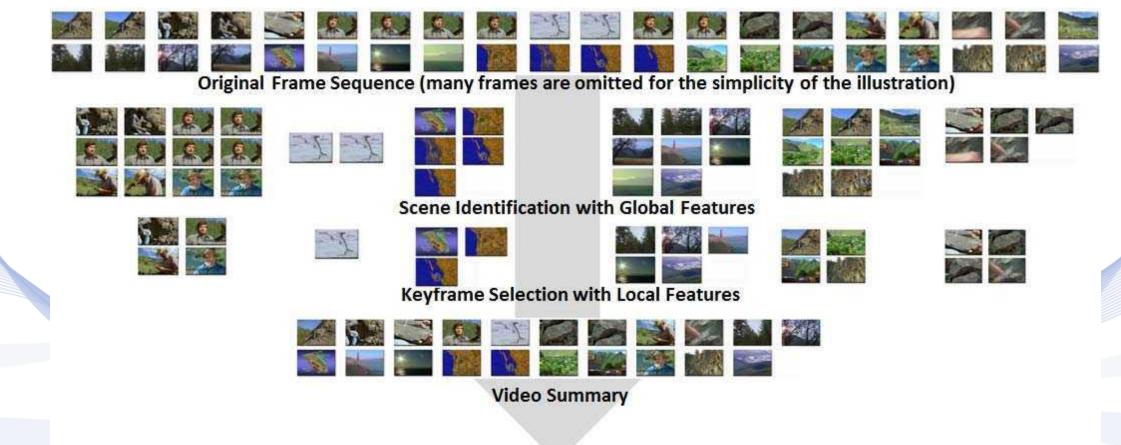


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- Multiple alternative algorithms exist both for temporal video segmentation and for content selection [KAI2012].
- All content selection algorithms for video summarization attempt to identify key-frames/shots/scenes, so that the final summary is:
 - **Representative** of the content of the full-length original video,
 - **Concise** in length (e.g., the number of key-frames may be 10% of the number of original video frames), and
 - Complete, in the sense that it covers the entire content of the original video (e.g., no sequence of a movie is completely left out of the summary).

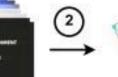




Video Summarization with Global and Local Features (Image from ResearchGate)







Video input

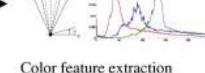
Static video summary composition

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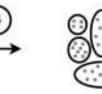
(temporal order)

Video frames pre-sampling



(color histogram, HSV, 16 bins)

(5)



Frames clustering (k-means, Euclidean distance)

Keyframe extraction

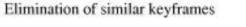




Image from Heartbeat-Fritz AI

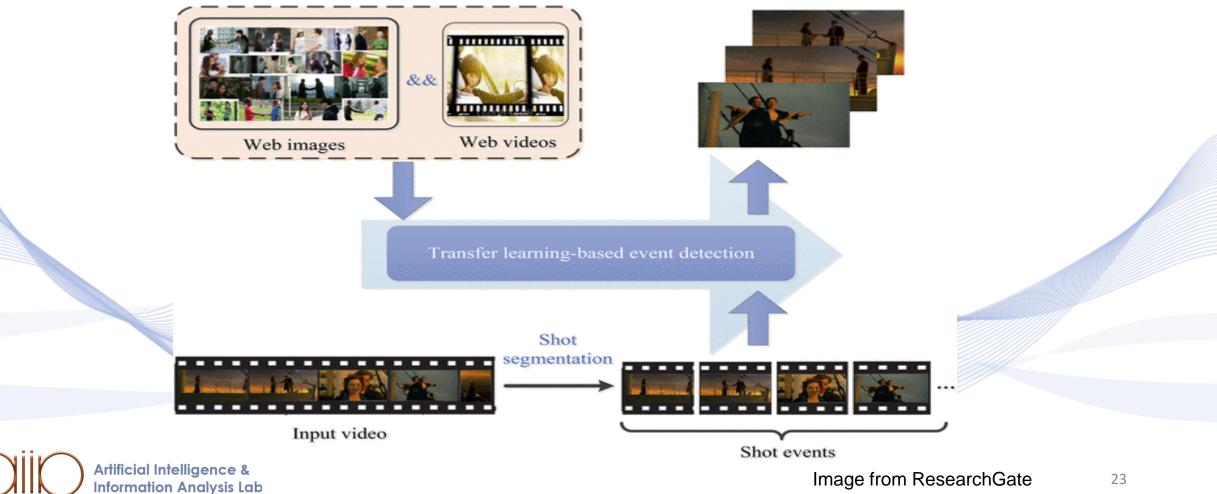
()



- Event-based summarization [BUR2020]
 - Visually *abnormal/rare events* are considered interesting (e.g., a robbery or traffic accident scene in a film).
 - The nature of such events depends on the employed video frame representations:
 - Low-level features expressing perceived motion, colors, etc.
 - Higher-level semantic features expressing visible objects, activities, etc.
 - · The selection algorithm retains in the summary only parts of the

original video that seem to contain abnormal content.

• Event-based video summarization







- **Object-based summarization** [BUR2020].
 - There are cases where we are only interested in the parts of the video depicting a specific family of objects (e.g., people).
 - An object detector is required to analyze each scene.
 - Only parts of the original video (frames or segments) containing the desired object(s) are retained in the summary.



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Object-based video summarization



(VML



- Attention-based summarization [BUR2020]
 - There are various ways to identify which parts of an original
 - video hold most of the users' interest when they view it.
 - The derived summary may only contain key-frames/shots that have been assigned a high attention score.
 - For example, motion attention models may be employed to

measure each shot's interest.





- Various content selection algorithms have been employed for video summarization.
- Video frame/shot/scene *clustering* (e.g., K-Means) is the simplest approach.
- More sophisticated methods (e.g., *spectral clustering*) have also been employed.
- Dictionary learning approaches are a good alternative to

clustering.

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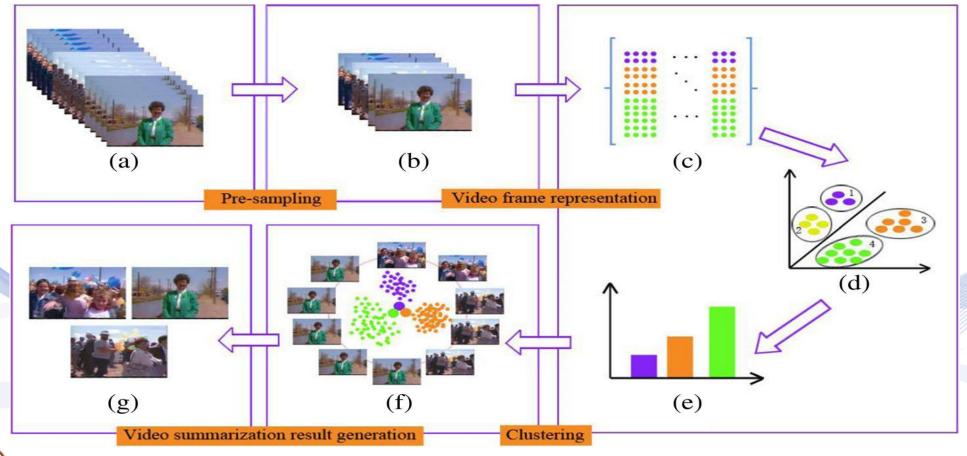


- All video frames are partitioned into clusters of similar properties and the medoid of each cluster is retained as a keyframe.
- Temporal subsampling may be applied before clustering, due to typically high similarities in the appearance of neighboring video frames.
- The exact same process may be applied at a shot or scene





• Clustering-based Video summarization.



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Image from Research Institute for Future Media Computing



- **Dictionary learning** is an effective replacement for clustering algorithms.
- The extracted key-frames form a *dictionary*.
- They should enable optimal reconstruction of the original video from the selected dictionary.
- Thus, the video summary is framed as the set of key-frames that can linearly reconstruct the full-length video in an algebraic





• Sparse dictionary learning.

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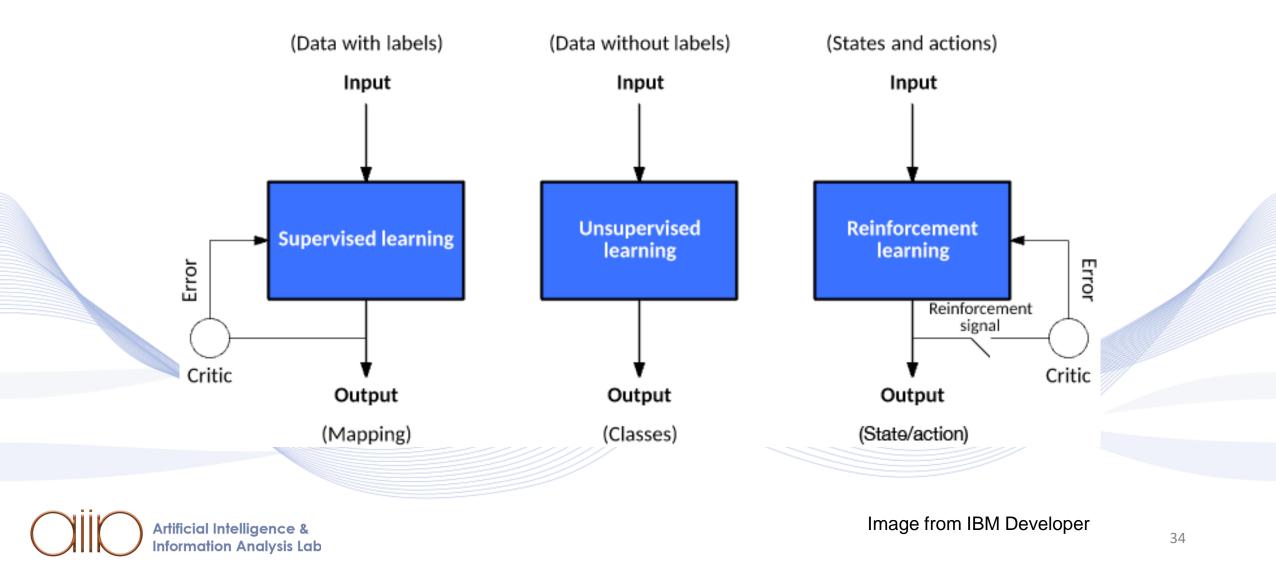
- Both clustering and dictionary learning are *unsupervised learning* approaches: no ground-truth summaries are required.
- The following approaches have also been proposed:
 - Reinforcement learning [WOR2020] or
 - supervised learning methods [DIN2019].

Supervised video summarization requires training of machine

learning model using a manually annotated training dataset.

The annotation may be an importance score assigned per video





- The standard supervised approach has several disadvantages.
- *Manual video annotation is quite expensive*, difficult and costly, especially if done at a per-frame level.
- Importance scores are quite subjective.
 - The trained model may only perform well in test videos resembling the training dataset.



Video Summarization with Deep Neural Networks



- In recent years, *Deep Neural Networks* (DNNs) have been employed for video summarization in various ways.
- The simplest approach is to exploit semantic video frame representations derived from pre-trained Convolutional Neural Networks (CNNs), as inputs to a traditional content selection algorithm.



Video Summarization with Deep Neural Networks



- A more sophisticated approach is to train a DNN under a supervised learning framework to directly regress an importance score for each original video frame.
- During the test stage, any video frame which is assigned a score larger than a threshold can be selected as a key-frame.
- · This approach has all the disadvantages of supervised



Video Summarization with Deep Neural Networks



- Various deep neural architectures may be combined in a composite DNN for video summarization. For example:
 - Convolutional Neural Networks (CNNs)
 - Transformers
 - 3D CNNs
 - Long Short-Term Memory Networks (LSTMs)
 - Generative Adversarial Networks (GANs).



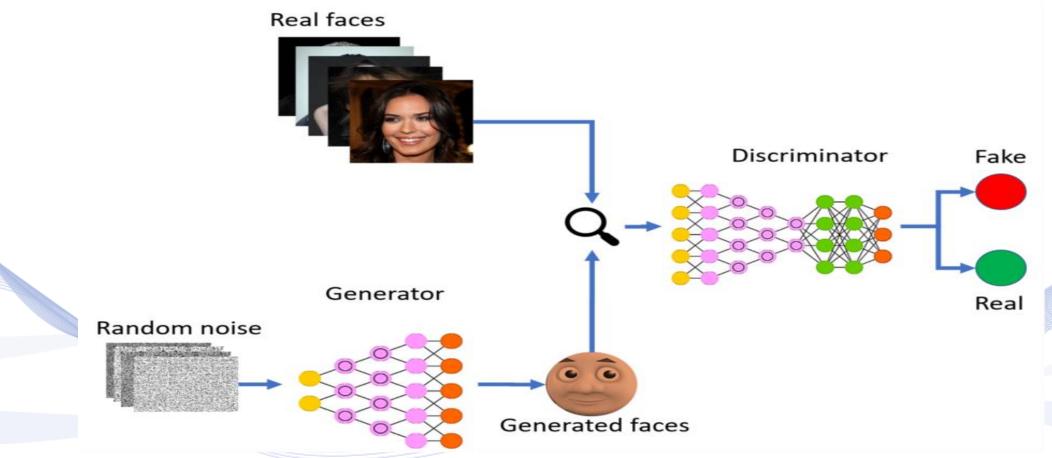
GANs for unsupervised video summarization



- **GANs combined with LSTMs** have recently been employed for unsupervised video summarization, using an end-to-end trainable DNN architecture.
- GANs are generative models which learn the distribution of the training data. They are composed of a Generator and a Discriminator involved in a minimax game.
 - The Generator learns to generate content that the Discriminator mistakes for real.
- After training, the Discriminator may be discarded.

GANs for unsupervised video summarization





Artificial Intelligence & Information Analysis Lab Image from LaptrinhX

GANs for unsupervised video summarization



Examples of fake faces



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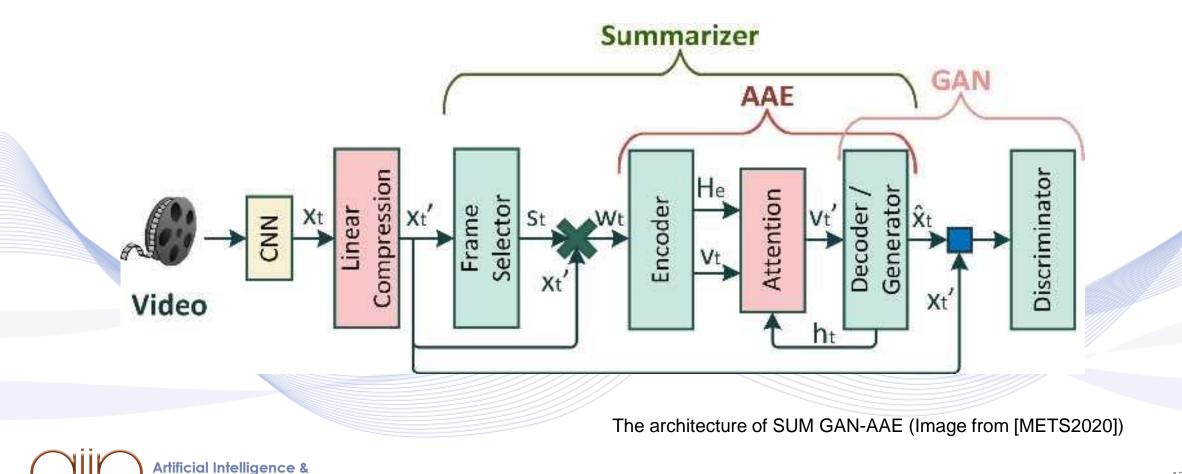
GANs for unsupervised video **VML** summarization

- SUM-GAN-AAE [METS2020].
- **Dilated Temporal Relational Adversarial Network** for framelevel video summarization [DIN2019].

• **Cycle-SUM**: Cycle-consistent Adversarial LSTM Networks for Unsupervised Video Summarization (Video Trailer) [PIN2019].



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- SUM-GAN-AAE is a modification of SUM-GAN [MAH2017].
- The network architecture consists in a Summarizer subnetwork, which acts as a Generator, and a Discriminator subnetwork.
- The Summarizer is a pipeline of three smaller subnetworks:
 - Frame Selector, Encoder, Decoder.
- All subnetworks are LSTMs.
- After training, only the Frame Selector is required.





• The Frame Selector receives sequentially as input the original video frame representations.

 For each input video frame, it estimates and outputs an importance score.

 The original video frame representations and the importance scores are multiplied.

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- produces a
- The Encoder is sequentially fed the above products and produces a fixed-length representation for the entire video.
- The representation produced by the Encoder is fed to the Decoder, which is equipped with an attention mechanism.

The Decoder is trained to sequentially output the original video frames.

 The Encoder-Decoder and the attention module jointly constitute the Attention Autoencoder subnetwork (AAE).

- VML
- Both the original and the reconstructed video frame representations are then sequentially passed to the Discriminator, whose task is to determine whether each sequence is "real" (original) or "fake" (summary-based reconstruction).
 - The Frame Selector and the AAE jointly constitute the Summarizer, which is trained to confuse the Discriminator.

• This forces the Frame Selector to learn how to extract representative keyframes, jointly capable of accurately reconstructing the full-length video.





- $\mathbf{X} \in \mathbb{R}^{M \times N}$: The input video data matrix.
- Each column $\mathbf{x}_i \in \mathbb{R}^M$ of the matrix \mathbf{X} , is the feature representation of the *i*-th frame.
- The baseline summarization architecture includes:
 - An LSTM-based *Frame Selector S* parameterized by weights w_s.
 - An LSTM-based **Encoder** E parameterized by weights w_e .
 - An LSTM-based **Decoder** D parameterized by weights w_d .
 - An LSTM-based *Discriminator* (binary classifier) *C* parameterized by weights w_c.



- S is fed x_i as input and outputs a corresponding scalar importance factor s_i ∈ [0, 1].
- The product $s_i \mathbf{x}_i$ is fed to *E* resulting in a state vector $\mathbf{e} \in \mathbb{R}^H$ encoding the summary.
- Subsequently, e is fed to D which attempts to reconstruct the original X, by outputting a reconstructed $\hat{\mathbf{x}}_i \in \mathbb{R}^M$, $1 \le i \le N$.
- Finally, the video reconstruction \widehat{X} is forwarded to the Discriminator *C* as a "fake" training example, while the original video X is used as a "real" training example.





- The following loss functions are employed during training:
 - Reconstruction loss:

$$\mathcal{L}_{recon} = \left\| \phi(\mathbf{X}) - \phi(\widehat{\mathbf{X}}) \right\|_{2}^{2},$$

- $\phi(\mathbf{X})$ is the last hidden LSTM state when it is fed **X** as input
- $\phi(\widehat{\mathbf{X}})$ the corresponding hidden LSTM state when *C* is fed $\widehat{\mathbf{X}}$.
- \mathcal{L}_{recon} is used to update $\mathbf{w}_s, \mathbf{w}_e, \mathbf{w}_d$.



Original video loss:

$$\mathcal{L}_{orig} = \left(1 - C(\mathbf{X})\right)^2.$$

- It is the MSE between the original video label (i.e., 1) and the discriminator output (in [0,1]) when C is fed X as input.
- \mathcal{L}_{orig} updates \mathbf{w}_c .
- Summary loss:

$$\mathcal{L}_{sum} = \left(C(\widehat{\mathbf{X}}) \right)^2$$

- is the MSE between the summary label (i.e., 0) and the computed probability when *C* is fed $\widehat{\mathbf{X}}$ as input.
- \mathcal{L}_{sum} updates \mathbf{w}_{C} .

Generator loss:



$$\mathcal{L}_{gen} = \left(1 - C(\widehat{\mathbf{X}})\right)^2.$$

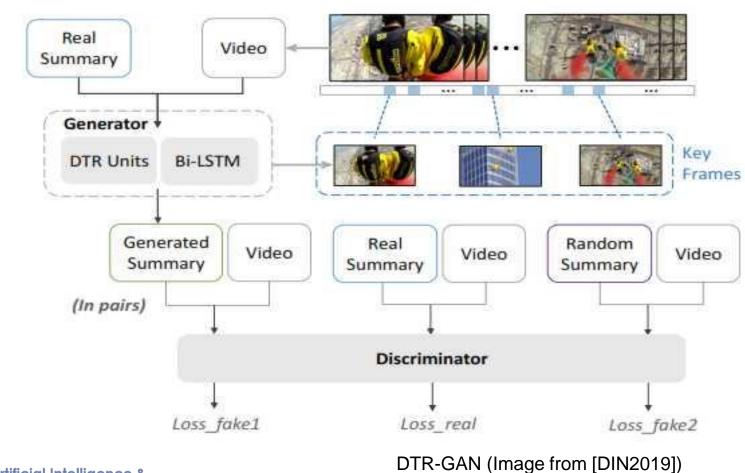
- It is the MSE between the original video label (i.e., 1) and the discriminator output, when C is fed $\hat{\mathbf{X}}$ as input. \mathcal{L}_{gen} updates the Decoder parameters \mathbf{w}_d .
- Sparsity Loss:

$$\mathcal{L}_{sparsity} = \left\| \frac{1}{N} \sum_{t=1}^{N} s_t - \sigma \right\|_2.$$

- It pushes the Selector towards assigning high importance (i.e., key-frame status probability) to a specific (*small*) percentage of the total number of original video frames, defined by a scalar hyperparameter *σ* ∈ [0, 1].
- Typically $\sigma \in [0.1, 0.2]$.
- $\mathbf{T}_{\mathbf{F}}$







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- The *Dilated Temporal Relational Generative Adversarial Network* (DTR-GAN) is an architecture slightly similar to SUM-GAN, but it is *supervised*.
- The Discriminator in DTR-GAN is trained with a composite threepart loss function, that takes jointly into account the generated summary, the ground-truth summary and a random summary.

This provides better regularization.

DTR-GAN



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- The Frame Selector is enhanced in DTR-GAN: besides the LSTMs, it also contains *Dilated Temporal Relational* (DTR) units.
- DTR units aim to exploit *long-range temporal dependencies*, complementing LSTMs.

They integrate context among video frames at multi-scale time spans, in order to enlarge the model's temporal field-of-view and, thus, effectively model temporal inter-frame relations.

DTR-GAN

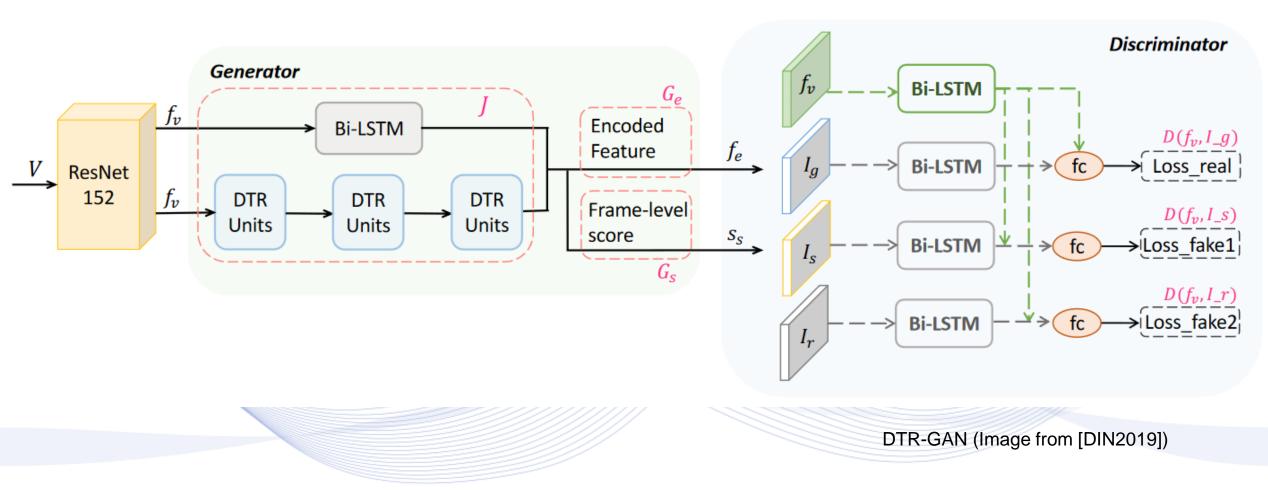
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- There is no LSTM auto-encoder in the DTR-GAN Summarizer, because the Discriminator is given *video* + *summary pairs* as inputs.
- Thus, the Discriminator learns to evaluate the correspondence between an input video and its summary,
 - rather than whether its input video has been reconstructed from a generated summary or not, as is the case in SUM-GAN-AAE.









Cycle-SUM

- Cycle-SUM is an unsupervised end-to-end trainable DNN for keyframe extraction, which extends the original SUM-GAN.
- During training, it replaces the unidirectional reconstruction of SUM-GAN/SUM-GAN-AAE (the original video is reconstructed from the generated summary) with a *"circular" bidirectional video reconstruction*.
- A cyclic consistency loss term is added to the training objectives of the overall framework.



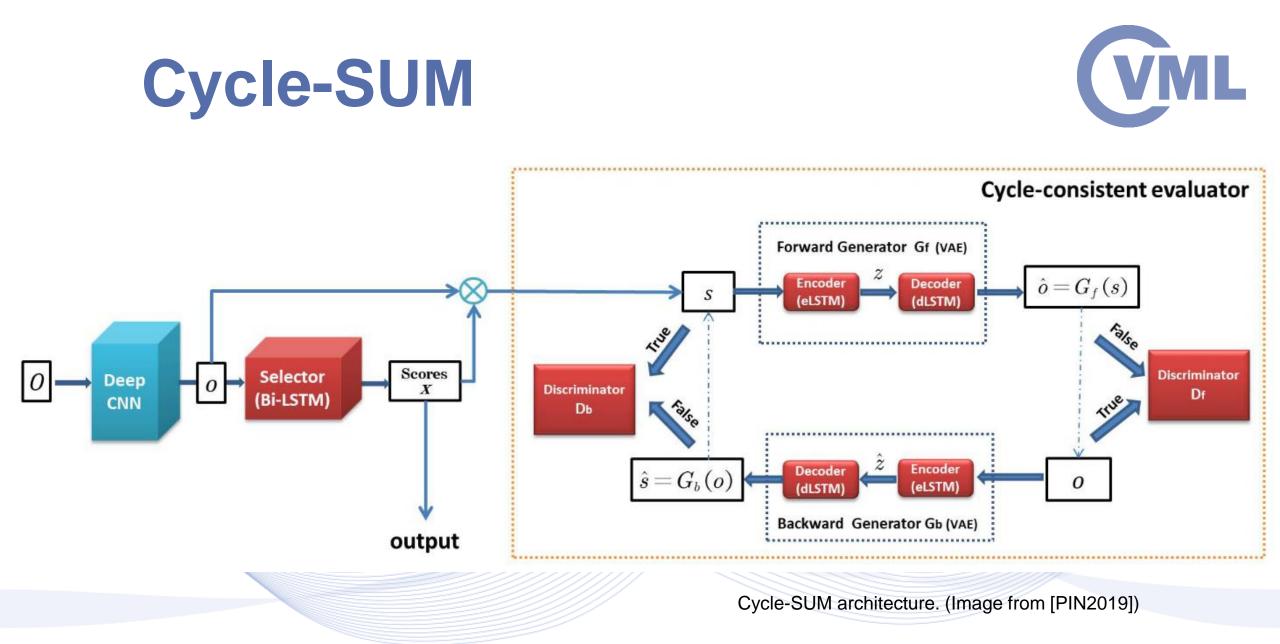


- Cycle-SUM is composed of an initial Frame Selector, two autoencoders (instead of one) and two Discriminators (instead of one).
- The *forward autoencoder* and Discriminator reconstruct the original video from the generated summary and evaluate it, respectively.
- The backward autoencoder and Discriminator reconstruct the summary from the original video and evaluate it, respectively.



- The closed training loop which enforces the cyclic consistency aids the DNN to *maximize mutual information between the summary and the original*, full-length video.
- Explicitly enforcing the reconstruction cycle original → summary → original → summary, better guarantees summary completeness and representativeness.





- Most DNN-based methods for video summarization emphasize representativeness, conciseness and completeness of the summary.
- However, it may be equally important that the selected keyframes are *diverse in visual content*.
- Summary variety makes it summary more interesting and reduces redundancy.



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 A straightforward way to achieve summary diversity with DNNs is to add the so-called *Determinantal Point Process* (DPP) loss term in the pool of training objectives.

In frameworks similar to SUM-GAN, the DPP loss directs the training process so that the Frame Selector learns to assign importance scores so that *the overall summary is diverse*.

• This diversity pertains to the semantic content captured in the input video frame representations (e.g., visible objects).



- The DPP loss operates by:
 - Quantifying the variance of the set of video frame representations.
 - Penalizing candidate key-frame sets/summaries that do not capture significant percentage of the original video variance.
- Consider a matrix $\mathbf{L} \in \mathbb{R}^{T \times T}$ by computing the pairwise cosine similarity for time step t and t' that is, $L_{ij} = \mathbf{e}_t^T \mathbf{e}_{t'}$.
- \mathbf{e}_t and $\mathbf{e}_{t'}$ are the Encoder's hidden states at time step t and t', respectively.

DPP loss:



$$\mathcal{L}_{dpp} = -\log\left(\frac{\det(\mathbf{L}_{y})}{\det(\mathbf{L}+\mathbf{I})}\right).$$

- L_y is a submatrix whose rows and columns are dictated by the indices of the selected keyframes and I is the identity matrix.
- Recently, the DPP loss was extended so that it also captures diversity of additional modalities, besides the CNN-derived representations expressing visible objects in each video frame.
- By enforcing diversity in the textual descriptions of each video frame, scene context and visible activities are also considered [KAS2022].
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- SUM-GAN-AAE is employed as a baseline and a pre-trained image captioner P is required.
- Then, the DPP-caption loss exhorts the video summary to be more diverse in terms of textual semantic content.
- During training, each video frame is forwarded to *P*, in parallel to feeding it to the Encoder.

 $\mathcal{L}_{dpp-c} = -\log \frac{\det(\mathbf{P}_y)}{\det(\mathbf{P}+\mathbf{I})}.$

• The following cost is used for Frame Selector weight update:



DNNs and dictionary learning **(VML**

- Integrating dictionary learning into unsupervised deep neural frameworks such as SUM-GAN-AAE, has also been attempted [KAS2021].
- Using SUM-GAN-AAE as a baseline, an additional pre-trained autoencoder is employed to pre-encode the entire video sequence into a single fixed-length vector h.
- During training, a novel loss term is added to the framework:

 $\mathcal{L}_{dict} = \|\mathbf{h} - \mathbf{A}\mathbf{e}\|_2.$

Vector e is given by the Encoder, while A is learnt.
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DNNs and dictionary learning **(VML**

- Matrix A transforms the current summary representation to a vector space being simultaneously learnt from all the original videos.
- A essentially serves as a *global visual dictionary*.
 - Thus, each summary representation is exhorted towards being a set of linear reconstruction coefficients that are jointly able to reproduce the corresponding original video representation.
- This is on top of the non-linear reconstruction objective enforced by the baseline SUM-GAN-AAE.



Action

An

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- Reinforcement learning (RL) has also been integrated into unsupervised deep neural frameworks for video summarization.
- In RL, a cognitive agent is trained through interaction: it interacts with its environment, in order to find a policy that maximizes a cumulative reward.
- The reward is a numerical measure that determines how good the agent's action was.

State

Sn

Reward

Rn

Environment

• The learned policy maps states to actions.

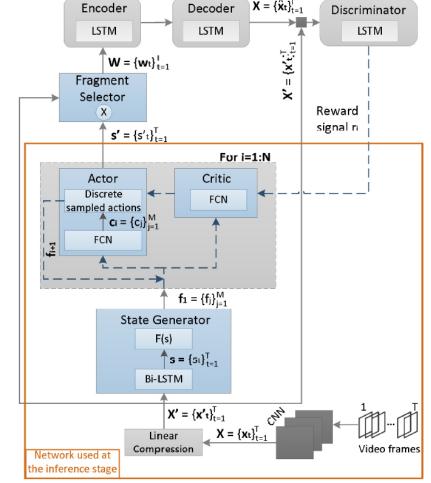


Environment-action interaction (Image from [SUT1998])

- AC-SUM-GAN is a good example of combining SUM-GAN with RL. [APO2020]
- A neural Actor-Critic architecture is embedded into SUM-GAN.
- During training, it learns the optimal policy for key-frame extraction.
- During inference, the RL agent modifies/adjusts the video frame importance scores outputted by the Frame Selector.







The architecture of AC-SUM GAN (Image from [APO2020])



- The Actor generates sequences incrementally, based on a set of discrete sampled actions over a group of video fragments.
- The Critic evaluates the Actor's choices and returns a value for scoring each choice, according to its impact on the action-state space.
- The Discriminator acts as the RL environment and returns a reward that is used to train the Actor-Critic model, which learns a value function (Critic) and a policy for key-fragment selection (Actor).

• The Critic can be discarded after training.



• The Actor plays an "N-picks" game to explore the action-state space.

- For every step i, $(1 \le i \le N)$:
 - It receives the current state $\mathbf{f}_i = \{f_j\}_{j=1}^M$, where *M* is the number of non-overlapping fragments into which the video is segmented.
 - At time i = 1, f_1 is derived from the vector of importance scores outputted by the Frame Selector.





- (continued)
 - It produces a distribution of actions $\mathbf{c}_i = \{c_j\}_{j=1}^M$.
 - It takes an action by sampling the computed distribution c_i, thus, picking a video fragment k for inclusion in the summary.
 - This action modifies the state and produces f_{i+1} .
 - During training, the reward is the Discriminator's classification decision.



- There are several public datasets for evaluating video summarization algorithms.
- Typically, these datasets provide a collection of videos with associated per-frame ground truth importance scores.
 - The most common ones are TVSum and SumMe.
 - **SumMe** includes 25 videos of 1 to 6 minutes duration with diverse video contents, captured both from first and third-person view.
 - **TVSum** consists of 50 videos of 1 to 11 minutes duration, containing video content from 10 categories of the TRECVid MED dataset.





- Every video of the dataset *is annotated by multiple users* in the form of key fragments (SumMe) or frame-level importance scores (TVSum)
 - Single ground-truth summaries are also provided.

To evaluate a video summarization algorithm, the generated summary for a given video is compared with the users' summary, separately per user.



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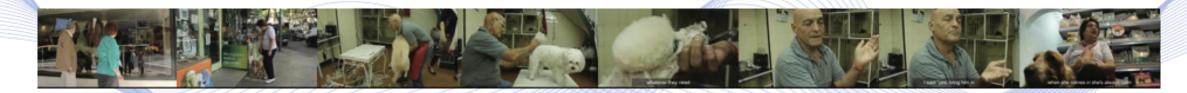
- An F-Score (F-measure) is computed for each pair of compared summaries.
- The computed F-Scores for TVSum are averaged or the maximum of them is kept for SumMe and a final F-Score is obtained for this video.
- The computed F-Scores for the entire set of testing videos are finally averaged to quantify the algorithm's performance.







Video frames from the sequence "Cooking" of the SumMe dataset.



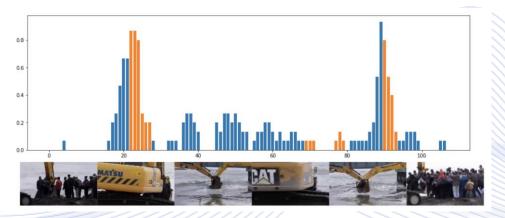
Video frames from the sequence "Dog grooming in Buenos Aires" of the TVSum dataset.







Video frames from the sequence "Excavators road crossing" of the SumMe dataset.



The video frame importance scores and the extracted summary using SUM-GAN-AAE in combination with \mathcal{L}_{dict} +

 \mathcal{L}_{dpp}



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Q & A

Thank you very much for your attention!

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